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| 1 | Smagorinsky Constant Distribution and Turbulent Energy Dissipation in High |
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| 2 | Reynolds-Number Cavity Flow |
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| 12 | |
| 13 | Abstract: This study experimentally investigates lid-driven cavity flow at high |
| 14 | Reynolds numbers ($Re = 3 \times 10^5$ to 1×10^6) using Particle Image Velocimetry (PIV). The |
| 15 | spatial distribution of root mean square (RMS) velocity, turbulent kinetic energy |
| 16 | dissipation rate, and the Smagorinsky constant is analyzed to reveal key turbulence |
| 17 | characteristics. Results show that: (1) The RMS velocity increases significantly in the |
| 18 | near-wall region with Reynolds number, reaching a peak of 0.43 m/s on the downstream |
| 19 | near-wall surface at $Re = 1 \times 10^6$, while remaining below 0.1 m/s in the core region due |
| 20 | to flow stability suppressing turbulence fluctuations; (2) The turbulent kinetic energy |
| 21 | dissipation rate exhibits significant spatial nonuniformity near the wall, with a peak |
| 22 | value of 0.6 at $Re = 1 \times 10^6$; as Reynolds number increases, high dissipation regions |
| 23 | extend further into the cavity interior and evolve into multiscale fragmented structures; |
| 24 | (3) The Smagorinsky constant is close to zero near the cavity wall, gradually increases |
| 25 | with distance from the wall, reaches a maximum, and then decreases to zero at the |

- cavity center. As Reynolds number increases, the overall Smagorinsky constant increases, with a more significant rise in its maximum value at higher Reynolds numbers, indicating stronger eddy viscosity. These findings provide experimental insights for improving the nonuniform parameterization in eddy viscosity models for large-eddy simulations.
- 31 **Keywords:** Lid-driven cavity flow; High Reynolds number; Particle Image Velocimetry;
- 32 Large Eddy Simulation; Smagorinsky constant

1. Introduction

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Turbulence is a complex and pervasive phenomenon found in both natural and 34 engineering systems, presenting significant challenges for numerical simulations in 35 fluid dynamics due to its multi-scale vortex interactions and energy cascade 36 characteristics (Smagorinsky, 1963). In practical application such as atmospheric 37 circulation, aircraft aerodynamics, and chemical reactor flows, traditional numerical 38 methods must balance accuracy and computational efficiency. While Direct Numerical 39 Simulation (DNS) can fully resolve the turbulence spectrum (Ghia et al., 1982), it 40 41 becomes prohibitively expensive at high Reynolds numbers. On the other hand, Reynolds-Averaged Navier-Stokes (RANS) methods, which rely on time-averaged 42 equations to reduce computational costs (Pan and Acrivos, 1967), fail to capture 43 transient turbulence fluctuations. Large Eddy Simulation (LES) has emerged as the 44 leading approach, as it directly resolves large-scale vortices while modeling the effects 45 of unresolved small-scale turbulence (Germano et al., 1991). However, the main 46

47 challenge in LES lies in the development of Subgrid-Scale (SGS) models and the 48 optimization of their empirical parameters to improve predictive capabilities. The 49 classical Smagorinsky model defines a nonlinear relationship between subgrid-scale 50 stress and strain rate tensors based on the hypothesis of eddy viscosity, where the empirical constant C_s directly influences turbulence energy dissipation rate (Wang et al., 51 2020). Early studies demonstrated success in homogeneous isotropic turbulence using 52 a fixed C_s value (ranging from 0.1 to 0.18) (Geurts et al., 1999), but faced significant 53 54 limitations in more complex flow scenarios. Malik et al. (2016) found that, while the Shear-Improved Smagorinsky Model (SISM) with C_s =0.18 could predict friction 55 velocity in plane channel flow with less than 3% error compared to reference DNS data, 56 it struggled to capture transient flow characteristics effectively when applied to 57 complex unsteady flows. Dallali et al. (2015) emphasized the importance of selecting 58 an appropriate C_s value for accurate turbulence simulations in sediment transport 59 60 studies. Collectively, these findings highlight the inherent limitations of the fixed C_s model in non-homogeneous and unsteady flows To improve model adaptability, the 61 62 dynamic Smagorinsky model optimizes the C_s value in real-time using double filtering 63 (Germano et al., 1991), enhancing accuracy in shear flows (Vreman et al., 2004). However, it faces challenges with parameter oscillations at extreme Reynolds numbers, 64 and deficiencies in the near-wall region persist. Hybrid models, such as Detached Eddy 65 66 Simulation (DES) combined with data-driven methods, provide new solutions. Beck et al. (2019) demonstrated that, with $C_s = 0.12$, a hybrid model incorporating an Artificial 67 Neural Network (ANN) closure term can stably simulate Decaying Homogeneous

69 Isotropic Turbulence (DHIT), significantly outperforming the standard Smagorinsky 70 model. Despite these advantages, fixed C_s coefficients still restrict adaptability, making it difficult to capture the dynamic characteristics of high Reynolds number flows. The 71 limitations of the fixed C_s model become more apparent in engineering practice. Bianco 72 et al. (2016) found that , with Cs = 0.1 in the double-loop vortex tube heat transfer 73 simulation, the prediction of heat transfer performance was biased, and this bias could 74 not be fully corrected even with grid refinement. Piomelli and Balaras (2002) pointed 75 out that in strong shear flows, C_s must be adjusted from 0.10 in the core flow region to 76 0.05 near the wall. This spatially varying adjustment not only increases computational 77 complexity but also leads to excessive suppression of turbulence fluctuations in the 78 79 near-wall region. Notably, the WALE model (Nicoud and Ducros, 1999) introduces the square of the velocity gradient tensor to construct subgrid viscosity, and its constant C_w 80 is optimized in the range of 0.55-0.60 for simulating decaying turbulence. However, 81 82 compared to the dynamic C_s adjustment strategy, it remains constrained by the inherent limitation of a fixed constant.. More recently, de Crouy-Chanel et al. (2024) calibrated 83 84 the VMS-Smag model ($C_s = 0.41$) using the remeshed vortex method, achieving optimal accuracy in simulating Taylor-Green vortices. Nonetheless, its applicability in wall-85 86 bounded flows still requires further validation. High Reynolds number lid-driven cavity 87 flow, a common flow pattern in applications like aircraft engine cooling channels and building ventilation systems (Spalart et al., 2006), exhibits characteristics of strong 88 inertial dominance, complex multi-scale vortex interactions, and poorly understood 89 energy dissipation mechanisms. Existing studies often use a fixed C_s=0.17 or empirical 90

91 damping functions to modify near-wall dissipation (Lund et al., 1998), but they face 92 dual challenges in practical applications. First, the fixed C_s value leads to excessive 93 suppression of turbulence fluctuations in the wall region (Sardina et al., 2012), which 94 affects the physical realism of vortex evolution. Second, the wall damping function is difficult to accurately define accurately in complex geometries (Vreman et al., 2004). 95 96 Although dynamic models improve the accuracy of shear flow simulations through local parameter optimization (Germano et al., 1991), the distribution of C_s values and 97 98 their dynamic correlation with flow field characteristics in high Reynolds number liddriven cavity flows have yet to be revealed. Recent research shows that most studies on 99 cavity flows focus on low to medium Reynolds numbers (Abdi et al., 2021; Carlos et 100 101 al.,2021; Trong et ak.,2020), and systematic experimental studies on high Reynolds number (Re≥1×10⁵) cavity flow are still scarce (Bouffanais et al., 2007; Wang et al., 102 103 2025; Samantaray et al., 2020). Particularly under the high Reynolds number condition of $Re=1\times10^5$, the distribution of C_s values and their dynamic correlation with flow field 104 105 features remain unexplored, lacking sufficient experimental research and in-depth 106 exploration.

To address these challenges, this study systematically invetigates high Reynolds number flow in a 0.25m lid-driven cavity at $Re=3\times10^5$ to 1×10^6 . Using PIV to obtain transient flow field data, it analyzes the spatiotemporal evolution of C_s values and develops a model linking them to local turbulence kinetic energy dissipation mechanisms. This approach more accurately capture turbulence's dynamic evolution and multi-scale coupling effects, overcoming the limitations of the traditional fixed C_s

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models. The results provide physical-driven optimization guidelines for dynamic subgrid models and advance turbulence simulations from empirical corrections to a mechanism-driven paradigm, laying the theoretical foundation for refined prediction of high Reynolds number complex flows.

117 2. Experimental Setupand Methods

118 2.1 Experimental Setup

The experiment was conducted in a recirculating cubic cavity flow system, with the cavity dimensions being 0.25 m in length, width, and height, as shown in Figure 1. The top cover of the cavity is driven by a belt that moves the fluid, with the belt speed adjustable to control the Reynolds number. To ensure stable water volume inside the cavity, unaffected by the driving mechanism, a large water tank was installed at the outer edge of the cavity's top cover. The belt is submerged in the water tank, ensuring that the water flow is not reduced due to fluid loss outside the tank. During the experiment, the belt speed was adjusted to bring the Reynolds number close to the preset value. Tracer particles with an appropriate concentration were added to the water, and after waiting for 10-15 minutes to allow the flow system to stabilize, the laser was adjusted to illuminate the tracer particles along the middle plane of the cavity, specifically at X=0, as shown in Figure 1. The belt rotates along the x-direction of the cavity. High-speed cameras were used to capture and store experimental images. The experiment was repeated for different Reynolds numbers, adjusting the test conditions to obtain flow field data for varying Reynolds numbers.

This experiment utilized a classical multi-channel 2D2C PIV system for flow field measurements. The system consisted of a high-speed frame-straddling camera, a continuous laser, a synchronizer, and a computer. The high-speed camera used was the M220M model produced by Zhongke JunDa Vision Technology Co., Ltd., equipped with a 50 mm F1.4 lens, providing a maximum image resolution of 1920 × 1080 pixels and a maximum frame rate of 1000 frames per second. For actual measurements, the image resolution was set to 1024 × 1024 pixels to balance computational accuracy and image processing efficiency. The PIV data processing employed the classical crosscorrelation algorithm, combined with a multi-level grid iterative image deformation method (Image Deformation Algorithm) to improve image processing accuracy. Additionally, sub-pixel precision localization techniques were used to further optimize the displacement calculation accuracy. To ensure smooth velocity field calculations, the window overlap rate was set to 25%. The laser source used was a continuous 532 nm green laser with a power of 8 W, providing stable illumination intensity. Hollow glass microspheres with a diameter of 10 µm and a density of 1.1 g/cm³, closely matching that of water, were chosen as tracer particles due to their excellent flow-following characteristics, allowing for precise tracking of fluid motion.Image acquisition was performed using the "JunDa High-Tech High-Speed Image Acquisition System V1.0" software developed by Zhongke JunDa Vision Technology Co., Ltd. (Huang et al., 2019). This system efficiently synchronized the laser and camera, ensuring accurate continuous image capture. With this setup, the experiment successfully observed typical vortex structures within the neutral-plane flow field, including the primary vortex (PV),

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157 unsteady vortex (UUV), along with other characteristic flow structures. The Reynolds numbers measured in this study are 3×10^5 , 5×10^5 , 7×10^5 , and 1×10^6 . 158 159 The Reynolds number is defined as Re=UL/v, where v is the kinematic viscosity and L160 is the length of the cavity. The required driving velocity can be calculated using this 161 formula. In the experiments conducted within the Reynolds number range of $Re = 5 \times 10^5$ to 162 1×10^6 , the velocity field was subjected to uncertainty quantification analysis using PIV. 163 Based on the time series statistics of multiple instantaneous velocity fields for each 164 165 condition, the spatially averaged standard deviation (σ_{avg}) ranged from 0.0263 to 0.0516 m/s, reflecting the variation in turbulence fluctuation intensity with Reynolds number. 166 The maximum relative error (ε_{max}) is below 1.5%. The PIV system was calibrated by 167 the National Institute of Metrology, and the system's accuracy remains stable, with a 168 relative error of -0.42% to -0.58% and repeatability < 0.33%, ensuring the reliable 169 170 accuracy of the high Reynolds number experimental results.

downstream secondary vortex (DSV), upstream secondary vortex (USV), and upstream

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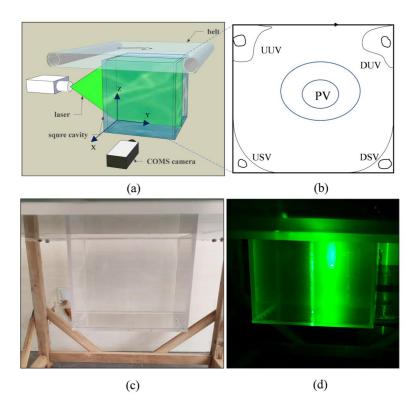


Fig. 1. Lid driven cavity. (a) Schematic of the experimental setup.(b) Vortex structure diagram. (c) Laboratory square cavity. (d) PIV imaging of the middle plane.

2.2 Large Eddy Simulation Governing Equations and Subgrid-Scale Stress

2.2.1 Governing Equations of Large Eddy Simulation

In LES, a spatial filtering operation decomposes the velocity field into a resolved large-scale component and an unresolved small-scale fluctuating component, which represents the subgrid-scale fluctuations. $u_i = \overline{u_i} + u_i'$ (1) where u_i represents the resolved large-scale low-pass filtered velocity, and $\overline{u_i}$

represents the unresolved small-scale residual fluctuations u_i .

- Assuming that the filtering process and the differentiation process can be interchanged, filtering the Navier-Stokes equations leads to the governing equations of LES.
- 185 $\frac{\partial \overline{u_i}}{\partial t} + \frac{\partial \overline{u_i u_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \overline{p}}{\partial x_i} + v \frac{\partial^2 \overline{u_i}}{\partial x_j \partial x_i}$ (2)

$$\frac{\partial \overline{u}_i}{\partial x_i} = 0 \tag{3}$$

- Let $\overline{u_i u_j} = \overline{u_i u_j} + (\overline{u_i u_j} \overline{u_i u_j})$. The term $-(\overline{u_i u_j} \overline{u_i u_j})$ is defined as the SGS, then
- Equation (2) can be rewritten as:

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$$\frac{\partial \overline{u_i}}{\partial t} + \frac{\partial \overline{u_i}\overline{u_j}}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \overline{p}}{\partial x_i} + \nu \frac{\partial^2 \overline{u_i}}{\partial x_j \partial x_i} - \frac{\overline{\tau}_{ij}}{\partial x_j}$$
(4)

- In the equation, $\overline{\tau_{ii}} = \overline{u_i u_i} \overline{u_i u_i}$ represents the SGS stress. To perform large eddy
- simulation, it is essential to construct a closure model.
- 192 2.2.2 Subgrid-Scale Stress Model in Large Eddy Simulation
- The most widely used subgrid-scale model is the Smagorinsky eddy viscosity
- 194 model (Shui et al.,2022).

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$$\overline{\tau_{ij}} = (\overline{u_i u_j} - \overline{u_i u_j}) = 2(C_s \Delta)^2 \overline{S}_{ij} (2\overline{S}_{ij} \overline{S}_{ij})^{1/2} - \frac{1}{3} \tau_{kk} \delta_{ij}$$
 (5)

- Here, Δ is the filter size, the subgrid-scale viscosity $v = (C_s \Delta)^2 (2\overline{S_u} \overline{S_u})^{1/2}$, and C_s is the
- 197 Smagorinsky constant, which corresponds to the mixing length.
- 198 2.3 Methods for Computing the Smagorinsky Constant
- The distribution of the C_s in the SGS energy flux and turbulence energy dissipation
- arate requires approach to compute the dissipation rate for closing the corresponding
- equations. The following section describes the formulas for calculating turbulence
- kinetic energy dissipation and the C_s in Large Eddy Simulation, as well as other

- 203 methods for computing turbulence kinetic energy dissipation.
- 204 2.3.1 Smagorinsky Constant in Large Eddy Simulation
- To study LES from the energy perspective, multiply both sides of equation (4) by
- the velocity $\overline{u_i}$ and simplify it, resulting in the kinetic energy balance equation:

$$\frac{\partial \overline{q}^{2}}{\partial t} + \overline{u}_{i} \frac{\partial \overline{q}^{2}}{\partial x_{i}} = \frac{\partial}{\partial x_{i}} (-\overline{p}\overline{u} + \frac{\partial \overline{q}^{2}}{\partial x_{j}} - \tau_{ij}\overline{u}_{i}) - \upsilon \frac{\partial \overline{u}_{i}}{\partial x_{j}} \frac{\partial \overline{u}_{i}}{\partial x_{j}} + 2\tau_{ij}\overline{S}_{ij}$$
 (6)

- The left-hand side of the equation represents the rate of change of kinetic energy with
- time and the convective transport term. The right-hand side includes work done by
- 210 pressure, viscous dissipation, work done by subgrid-scale stress, and the vortex
- 211 dissipation term representing the transfer of large-scale turbulence kinetic energy to
- small scales. In Large Eddy Simulation, the turbulence kinetic energy dissipation rate
- 213 can be approximately represented by the SGS energy dissipation rate (Meneveau and
- 214 Katz, 2000).

$$\varepsilon \approx \langle \varepsilon_{SGS} \rangle = -2 \langle \tau_{ii} \overline{S_{ii}} \rangle \tag{7}$$

- In the Smagorinsky model, the subgrid-scale stress is given by $\tau_{_{ij}} = -C_{_i}^2 \Delta^2 |\overline{S}| \overline{S}_{_{ij}}$.
- 217 2.3.2 Calculation Methods for Dissipation Rate ε
- 218 (1) Dimensional Analysis Method
- In the study of turbulence dissipation rate, the dimensional analysis method
- 220 provides a way to express it using the Taylor scale and turbulent velocity. The
- turbulence dissipation rate can be expressed as:

$$\varepsilon = 15v \frac{u^2}{\lambda^2} \tag{8}$$

Here, λ represents the Taylor scale. According to the balance turbulence scales

224 (Konstantinos, 2022; Rubinstein and Clark,2017), equation (8) can be further 225 transformed as follows:

$$\varepsilon = A \frac{u^3}{l} \tag{9}$$

Here, l represents the integral scale, and A is a constant close to 1.

228 (2) Large Eddy PIV Method

The velocity field obtained using PIV is low-pass filtered, similar to LES. As a result, only larger scales flow structures are resolved, with vortices smaller than the filtering scale are excluded. In high Reynolds number flow fields, turbulence kinetic energy is generated at the integral scale and dissipates near the Kolmogorov scale, with energy conservation between the two (Sikiö et al., 2018). An inertial subrange exists between these scales, where energy is transferred from larger to smaller scales without being generated or dissipated (Buaria and Sreenivasan, 2020). Therefore, when estimating the dissipation rate, it is sufficient to calculate the energy flowing through the inertial subrange, without needing to precisely resolve the Kolmogorov scale.

Sheng et al. (2000) proposed the Large Eddy PIV method, which uses data obtained through PIV measurements to directly calculate the turbulence dissipation rate. The point velocity in the actual fluid can be represented by the velocity measured using PIV:

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$$u_i = U_i - \Phi(U_i) + \frac{1}{2!} \Phi^2(U_i) - \frac{1}{3!} \Phi^3(U_i) + \cdots$$
 (10)

where, $\Phi(U_i) = (a_i \partial^2 / \partial x_1^2 + a_2 \partial^2 / \partial x_2^2 + a_3 \partial^2 / \partial x_3^2)U_i$, here U_i is the velocity obtained using PIV, and a_1 , a_2 , a_3 are constants related to the low-pass filtering width in the three

directions. These constants are typically expressed in a unified form as:

$$a_i = \frac{\Delta_i^2}{8}, i = 1, 2, 3, \tag{11}$$

Here, Δ_i is the filter width, and substituting it into the equation gives:

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$$u_{i} = U_{i} - \frac{\Delta^{2}}{8} L^{2} \overline{\nabla}_{i} + \frac{\Delta^{4}}{1024} \nabla^{4} U_{i} + \cdots$$
 (12)

- Based on dimensional analysis, the second term in equation (12) is approximately
- related to Δ^2/l^2 , where l is the integral scale and Δ is the filter scale. Since $\Delta \Box l$,
- there is a magnitude difference, allowing the second term and all subsequent terms to
- be approximated as 0, leading to:

$$\langle u_{i} \rangle \approx \langle U_{i} \rangle$$

$$u_i \approx U - \langle U_i \rangle \tag{13}$$

$$\langle u_i u_i \rangle \approx U_i U_i - \langle U_i \rangle \langle U_j \rangle$$

- The filtered Navier-Stokes equations can be represented using the PIV
- 257 measurement data as follows:

$$\frac{\partial U_i}{\partial x_i} = 0 \tag{14}$$

$$\frac{\partial U_i}{\partial t} + \frac{\partial (U_i U_j)}{\partial x_j} = -\frac{\partial P}{\partial x_j} + \upsilon \frac{\partial^2 U_i}{\partial x_j^2} - \frac{\partial \tau_{ij}}{\partial x_j}$$
 (15)

260 Correspondingly, the energy balance equation can be expressed as follows:

$$\frac{\partial \overline{q}^{2}}{\partial t} + U_{j} \frac{\partial \overline{q}^{2}}{\partial x_{i}} = \frac{\partial}{\partial x_{i}} (-PU_{j} + \upsilon \frac{\partial \overline{q}^{2}}{\partial x_{i}} - \tau_{ij} U_{i}) - \upsilon \frac{\partial U_{i}}{\partial x_{i}} \frac{\partial U_{i}}{\partial x_{j}} + 2\tau_{ij} \overline{S}_{ij}$$
(16)

- where $\overline{S}_{ij} = \frac{1}{2} \left(\frac{\partial U_{j}}{\partial x_{i}} + \frac{\partial U_{i}}{\partial x_{j}} \right)$ denotes the strain rate tensor derived from measurements.
- The last term in the equation represents the viscous term. It indicates the energy
- transferred from the resolved scale to the small scales, and also represents the SGS
- energy flux. The momentum transport can be expressed through this energy flux:

$$\varepsilon \approx \langle \varepsilon_{SGS} \rangle = -2 \langle \tau_{ii} \overline{S_{ii}} \rangle \tag{17}$$

267 2.3.3 Smagorinsky Constant Calculation Formula

The C_s is calculated by closing the equations using the dimensional analysis method and the Large Eddy PIV method. The two equations are solved simultaneously:

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$$\varepsilon = A \frac{u^{3}}{l} = -2\langle \tau_{ij} \overline{S_{ij}} \rangle = 4C_s^2 \Delta^2 \langle (\overline{S_{ij}} \overline{S_{ij}})^{3/2} \rangle$$
 (18)

Here, u' is the root-mean-square velocity, and Δ is the filter width. The following analyzes each term in the equation.

(1) Root Mean Square Velocity

The Root Mean Square (RMS) Velocity quantifies the magnitude of velocity fluctuations in turbulent flows, serving as a key metric for characterizing turbulence intensity. The calculation formula is as follows:

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$$u_{ij}' = (\overline{u_{ij}'^2})^{\frac{1}{2}} = \sqrt{\frac{1}{N} \sum_{n=1}^{N} (u_{ij})^2}$$
 (19)

In PIV experiments, the velocity field measurements typically include instantaneous velocity and time-averaged velocity. The velocity obtained from PIV measurements can be expressed as:

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$$u_{ij}' = (\overline{u_{ij}'^2})^{\frac{1}{2}} = \sqrt{\frac{1}{N} \sum_{n=1}^{N} (U_{ij})^2}$$
 (20)

where U_{ij} is the time-averaged velocity obtained from PIV measurements. Significant fluctuations in flow velocity and the potential periodic variations make it insufficient to simply average a large amount of long-term data when processing PIV results. In this experiment, to obtain a more accurate time-averaged velocity, we employed a local averaging method. For each time t, the data from 10 time steps before and after t are selected, and the average velocity over thoese 21 time steps is calculated to represent the average velocity at t. This method effectively reduces the impact of random fluctuations in instantaneous velocity, making the resulting time-averaged velocity more representative, resulting in a more accurate calculation of the root mean square

velocity.

(2) Integral Length Scale l

The integral length scale is an important parameter for describing turbulence characteristic (Arun et al., 2023), and is commonly represented by the integral of the autocorrelation coefficient of the velocity between two arbitrary points. The autocorrelation function $R(\Delta r)$ reflects the correlation between the velocities at two points, and is expressed as:

$$R(\Delta r) = \frac{\overline{u_i'(x,t)u_i'(x+\Delta r,t)}}{\sqrt{u_i'^2(x,t)u_i'^2(x+\Delta r,t)}}$$
(21)

Here, $R(\Delta r)$ represents the autocorrelation coefficient between two points separated by a distance $r\Delta$, and $u_i^{'}$ represents the fluctuating velocity, which is the instantaneous velocity minus the mean velocity. The superscript indicates the time average over different time scales. By subtracting the time-averaged velocity from the instantaneous velocity at each time step, the fluctuating velocity is obtained, and the autocorrelation coefficient is computed from these fluctuating velocities.

The calculation formula for the integral length scale l is:

$$l = \int_{0}^{\Delta r_{\text{max}}} R(\Delta r) d\Delta r \tag{22}$$

in which, Δr_{max} is the distance where the autocorrelation function first equals 0. In theory, when the two points are at a distance of 0, the autocorrelation function equals 1; when the distance approaches infinity, the autocorrelation function equals 0.

(3) Turbulence Kinetic Energy Dissipation Rate Using the Scale Similarity Method

Dimensional analysis is an important method in the study of turbulence dissipation rate. Using equation (9) to calculate the turbulence kinetic energy dissipation rate helps to understand the characteristics of turbulent energy dissipation.

(4) Strain rate tensor

315 The strain rate tensor is expressed as:

$$\overline{S}_{ij} = \frac{1}{2} \left(\frac{\partial U_j}{\partial x_i} + \frac{\partial U_i}{\partial x_j} \right) \tag{23}$$

The experiment uses two-dimensional PIV to observe the flow field, and the flow velocity within the plane has been determined. Therefore, \bar{S}_{ij} for i, j = 1, 2 is,

$$\overline{S}_{11} = \frac{\partial U_1}{\partial x_1}$$

$$\overline{S}_{12} = \overline{S}_{21} = \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_1} \right)$$

$$\overline{S}_{22} = \frac{\partial U_2}{\partial x_2}$$
(24)

320 3.Results and Discussion

- 321 3.1 Root Mean Square Velocity
- 322 3.1.1 Centerline Flow Velocity

Figure 2 shows the distribution of the RMS velocity along the centerline of the cavity. Experimental analysis reveals significant differences in the distribution of RMS velocity along the cavity centerline, particularly between the near-wall region and the primary vortex core region. In the near-wall region, both $u_{\rm rms}$ and $v_{\rm rms}$ reach their maximum values, with $u_{\rm rms}$ at the bottom wall increasing from 0.19 m/s at $Re = 3 \times 10^5$ to 0.35 m/s at $Re = 7 \times 10^5$. As the Reynolds number increases, particularly in the near-wall region, the values of $u_{\rm rms}$ and $v_{\rm rms}$ increase significantly. Specifically, $v_{\rm rms}$ reaches its peak near the downstream wall; at $Re = 5 \times 10^5$, the peak value at the upstream wall is 0.19 m/s, while at the downstream wall, it is 0.24 m/s. The peak at the downstream wall is slightly higher than at the upstream, indicating that turbulence fluctuations are most intense in this region. This trend is consistent with the experimental data of Prasad and Koseff (1989).

However, near the wall (at x = 0 or y = 0), due to flow resistance and the enhanced

end-wall effect, the RMS velocity quickly decays to nearly zero. The RMS velocity in the primary vortex core region (at x = 0.5 or y = 0.6) is significantly lower than in the near-wall region, as the main vortex structure suppresses turbulent fluctuations, and the RMS velocity in this region is less influenced by changes in Reynolds number. At high Reynolds numbers, the end-wall effect increases, leading to energy loss due to highfrequency fluctuations in the boundary layer, and reduced momentum redistribution, which decreases the velocity in the primary vortex core. In contrast, in the near-wall region, the RMS velocity rises rapidly due to the enhanced wall shear stress and turbulent intensity. These factors together cause a significant increase in RMS velocity near the wall. As the Reynolds number increases, the turbulence shear effect in the nearwall region intensifies, exacerbating boundary layer instability and causing turbulent kinetic energy accumulates, further increasing the fluctuation velocity. However, in the primary vortex core, due to the limited turbulence energy transport and lower momentum redistribution efficiency, the velocity distribution remains relatively stable. The results of this study align with the findings of Samantaray and Das (2019) and Padilla et al. (2005) regarding low Reynolds number cavity flows, where the RMS velocity is higher in the near-wall region and lower in the primary vortex core. At Re = 10000, the RMS velocity in the primary vortex region is smaller compared to the peak value at the wall, but the difference is relatively small (Samantaray et al., 2020). This is because at low Reynolds numbers, viscous effects dominate, and the turbulence characteristics in the primary vortex region and the near-wall region are more similar.

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in the primary vortex region is significantly lower than the peak value at the wall, with a larger difference. This is because in high Reynolds number flows, inertial forces dominate the evolution of turbulence, and the shear effects in the primary vortex region, which is far from the wall, are weaker, leading to lower turbulent fluctuation intensities. Meanwhile, in the wall region, turbulence intensity is higher due to stronger wall shear effects.

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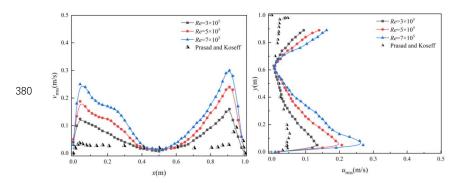
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In high Reynolds number flows ($Re = 3 \times 10^5$ to 7×10^5), the velocity difference between the left and right wall is smaller, indicating that the flow has entered a fully developed turbulent state, and intense turbulent fluctuations promote lateral momentum exchange, reducing local flow differences between the two walls. This contrasts with the low Reynolds number flows, where viscous effects are predominant. In low Reynolds number conditions, the flow near the walls is significantly influenced by local vortex structures, leading to greater velocity differences. Moreover, compared to the research by Samantaray et al. (2004) on square lid-driven cavities, although their experimental Reynolds numbers were lower (Re = 1000 to 15000), the variation of RMS velocity with Reynolds number showed consistent trends: as Reynolds number increased, turbulence intensity increased, and RMS velocity near solid boundaries significantly increased, while the RMS velocity in the cavity center was less influenced by changes in Reynolds number. This study further confirms that at high Reynolds numbers, the fluctuation velocity in the near-wall region increases significantly, while the core region exhibits weak dependence on Reynolds number due to flow stability limitations.



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Figure 2: Root Mean Square Velocity along the Centerline , including $u_{\rm rms}$ and $v_{\rm rms}$ Regarding the two components of RMS velocity, Padilla and Martins (2005) found that when using the Smagorinsky subgrid model with a constant $C_s = 0.1$, the peak value near the wall was lower than that near the primary vortex, with v_{rms} reaching 0.03 m/s near the primary vortex. Similarly, at $C_s = 0.18$, the peak velocity at x = 0.25 reached 0.32 m/s, which was significantly higher than the value near the left wall, indicating higher turbulence viscosity, which led to poor velocity statistics. As shown in Fig. 3, when using the dynamic subgrid model, the RMS velocity near the vortex center was lower than the velocity at the two side walls. In the case of different C_s values and the dynamic subgrid model, the peak values at the two side walls were very similar, with the $v_{\rm rms}$ difference on the left side being only 0.003 m/s. Only at locations further away from the side walls did the results from the dynamic subgrid model align better with the experimental data. Similarly, for the vertical neutral line y, the variation of u_{rms} follows the same trend as v_{rms} along the neutral line x. When $C_s = 0.18$ and using the dynamic subgrid model, the peak value errors at the top and bottom walls were small, with the error at the bottom wall side being only 0.01 m/s. Further away from the side walls, the velocity gradually decreased. When using the dynamic subgrid model, the peak

value of u_{rms} was much larger compared to the flow velocity interpolation at the vortex core,

398 with significant differences when $C_s = 0.1$ and $C_s = 0.18$.

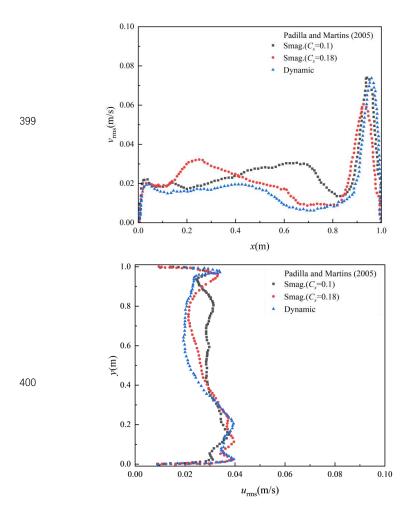


Figure 3: The vertical velocity along the neutral plane at Re = 10,000, as presented in the data from Padilla and Martins (2005).

3.1.2 Flow Velocity on the Middle Plane

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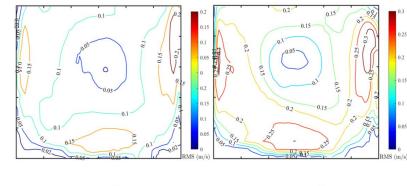
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Figure 4 presents the distribution of the RMS velocity (w_{rms}) on the middle plane (X=0) under different Reynolds numbers ($Re=3\times10^5$, 5×10^5 , 7×10^5 , 1×10^6). Experimental results indicate a significant spatial non-uniformity in the RMS velocity across different flow conditions. The fluctuation intensity in the primary vortex core region is relatively low, whereas noticeable peaks in the RMS velocity appear in the near-wall regions, particularly along the downstream wall. Specifically, at Re=3×10⁵, the maximum RMS velocity is approximately 0.24 m/s, and as the Reynolds number increases to 1×106, the peak value rises to around 0.43 m/s, with the maximum always occurring near the downstream wall. This phenomenon may be attributed to the jet effect induced by the lid-driven flow, which generates a localized high shear region that leads to a sharp gradient in velocity near the right wall, forming a tightly spaced contour of velocity gradients. As the Reynolds number increases, the trend of increasing RMS velocity in the near-wall region becomes more pronounced, and the complexity of the contour distribution and shape also increases, further suggesting that at high Reynolds numbers, the spatial non-uniformity and dynamic evolution of turbulence fluctuations are enhanced. The increase in Reynolds number strengthens the inertial forces dominating the turbulent transport mechanism. In the near-wall region, the interaction between wall shear and the turbulent boundary layer intensifies the accumulation of velocity gradients and fluctuation energy, leading to a significant increase in RMS velocity with higher Reynolds numbers.

Specifically, at high Reynolds numbers, the frequency of turbulent vortex

breakdown and reorganization within the boundary layer increases, causing the fluctuation energy in the near-wall region to spread across a wider frequency range, thereby enhancing the local velocity fluctuation intensity. In contrast, the primary vortex core, being farther from the wall shear influence, exhibits higher flow stability. Therefore, the RMS velocity in this region is less dependent on Reynolds number. However, as the Reynolds number increases to 1×10^6 , the turbulent mixing effects in the primary vortex region still lead to a slight increase in RMS velocity. This result highlights the competing mechanism between inertial and viscous forces in controlling the spatial distribution of turbulent energy. At high Reynolds numbers, the viscous dissipation effect near the walls weakens, and the inertial-dominated turbulent transport mechanism governs the distribution of energy. On the other hand, the core region is constrained by the momentum of the primary vortex structure, with its fluctuation evolution being dominated by local flow stability.



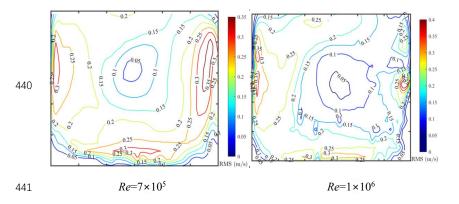
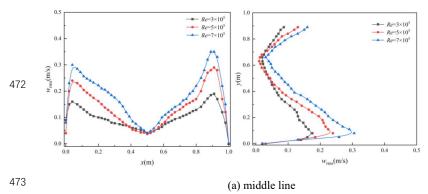


Figure 4: Root Mean Square Velocity on the Middle Plane

To gain deeper understanding of the distribution characteristics of the root mean square velocity (w_{rms}) at different positions on the cavity's middleplane, Figure 5 shows the evolution of w_{rms} along the middle line and near the side wall lines (x=0.91, y=0.11) under various conditions (Re=3×10⁵, 5×10⁵, 7×10⁵). The experimental results indicate that the w_{rms} along the side wall near the cavity exhibits a typical single-peak distribution (Figure b). Starting from the side wall (x = 0, y = 0), the w_{rms} gradually increases as the distance from the wall increases, reaching a peak near the core of the main vortex (at Re = 7×10⁵, the peak is approximately 0.37 m/s), and then gradually decays towards the opposite side wall. This phenomenon is attributed to the dynamic balance between the viscous effects in the near-wall region and turbulent energy transport. Near the wall, the viscous sublayer dampens the initial fluctuation intensity due to strong shear forces. As the distance from the wall increases (approximately x > 0.2 or y > 0.2), the viscous constraints weaken, and the inertial-dominated turbulent fluctuations rapidly accumulate, leading to a significant increase in w_{rms} . When the flow

reaches the main vortex region, the velocity reaches its maximum value. As the fluid continues to approach the wall (x > 0.6 or y > 0.6), the flow stabilizes, the momentum redistribution efficiency decreases, and the fluctuation energy dissipates gradually.

Notably, the $w_{\rm rms}$ distribution along the middle line exhibits a "bimodal" characteristic (Figure a). Specifically, the velocity near the side walls is relatively high (approximately 0.36 m/s), while the velocity in the main vortex core region (0.4 < x < 0.6 or 0.5 < y < 0.7) significantly decreases to below 0.1 m/s. This difference arises from the momentum constraint effect of the main vortex structure on the flow in the core region, which suppresses the multi-scale evolution of turbulent fluctuations. In contrast, near the side walls, the shear layer instability and enhanced turbulent mixing significantly amplify the fluctuation characteristics. Further analysis shows that as the Re increases from 3×10^5 to 7×10^5 , the peak value of $w_{\rm rms}$ exhibits a systematic increase. The peak value at the main vortex position along the side wall line x = 0.91 increases from 0.19 m/s at Re = 3×10^5 to 0.33 m/s at Re = 7×10^5 , while the $w_{\rm rms}$ along the side wall line y = 0.11 increases from 0.18 m/s to 0.35 m/s.



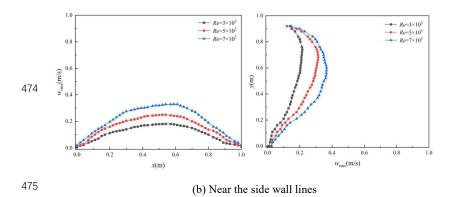


Figure 5: Root Mean Square Velocity at Different Locations on the Middle Plane 3.2 Dissipation Rate(ε)

Figure 6 shows the spatial distribution of turbulence kinetic energy dissipation rates(ε) in the cavity at different Reynolds numbers ($Re=3\times10^5$, 5×10^5 , 7×10^5 , 1×10^6). The experimental results indicate significant spatial non-uniformity in the ε : the ε in the main vortex region is generally below 0.1, while in the near-wall regions (near the bottom and side walls), the ε increases substantially, with the peak reaching 0.6 at $Re=1\times10^6$. As the Reynolds number increases from 3×10^5 to 1×10^6 , both the overall ε and its spatial complexity increase. Specifically, the ε near the bottom wall increases from 0.33 at $Re=3\times10^5$ to 0.68 at $Re=1\times10^6$. At $Re=3\times10^5$, the dissipation of turbulent kinetic energy is mainly concentrated near the wall, with the ε at the left side wall being only 0.15 and covering a small area. When the Reynolds number increases to 5×10^5 , the ε increases significantly, and the high dissipation area expands. At $Re=7\times10^5$, the high dissipation region at the left wall extends inward into the cavity, and two dissipation peak zones form on the left wall. At $Re=1\times10^6$, the high dissipation regions

fragment, and multiple localized high dissipation zones appear on the bottom and side walls, with the contour lines evolving from continuous bands to multi-scale fragmented structures, reflecting the dynamic evolution of the turbulence multi-scale vortex structures.

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The near-wall regions experience high dissipation rates due to the boundary layer, where the velocity gradient is steepened by wall shear. In these regions, viscous dissipation dominates the energy loss, leading to a significant increase in the local dissipation rate. As the Reynolds number increases, turbulence fluctuations dominated by inertial forces enhance, making the flow more prone to turbulence and vortex formation. The interaction, stretching, and breaking of these vortices cause rapid energy dissipation, leading to an increase in the dissipation rate. In the near-wall regions, the turbulence activity within the boundary layer intensifies as Reynolds number increases, enhancing viscous dissipation and thus increasing the dissipation rate. Moreover, at high Reynolds numbers, the flow instability intensifies, leading to the emergence of smaller-scale vortex structures within the cavity, further enhancing energy dissipation. A comparison with Samantaray et al. (2019) in their study of cavity flows at $Re \le$ 1.5×10⁴ reveals a common trend of significant increases in dissipation rates near the wall. This study further shows that the high dissipation regions extend from near the wall into the cavity as Reynolds number increases, and more regions inside the cavity show a significant rise in turbulence dissipation rates, with more intense changes in contour lines. Additionally, Gnanasekaran and Satheesh (2024) found in their numerical study of turbulence in double-cavity flows that, under specific length-to-width and

velocity ratio conditions, the dissipation rate may decrease as the Reynolds number increases. This phenomenon is likely related to the geometric configuration of the double cavity and its effect on the stability of the main vortex structure, which may inhibit the development of turbulence and thus weaken energy dissipation. The results of this study show that, in a single-sided driven cavity, the positive reinforcing effect of Reynolds number on dissipation rates dominates, further highlighting the significant influence of geometric configuration and driving conditions on turbulence dissipation mechanisms.

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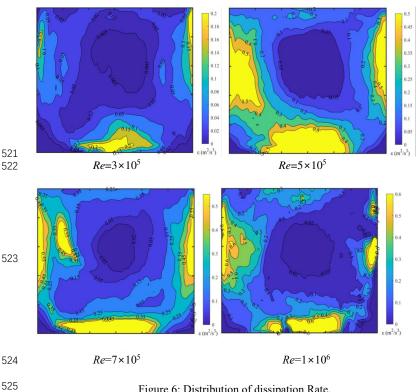


Figure 6: Distribution of dissipation Rate.

3.3 Smagorinsky Constant

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Figure 7 shows the distribution of the Smagorinsky constant in the cavity at different Reynolds numbers (Re=3×10⁵, 5×10⁵, 7×10⁵, 1×10⁶). At each Reynolds number, the Smagorinsky constant exhibits a distinct non-uniform distribution within the cavity. In the boundary regions, the value is relatively small. Starting from the boundary, as the distance from the wall increases, the constant first increases and then decreases. The region closest to the boundary is where turbulence and viscosity are the most intense, and the Smagorinsky constant reaches its maximum value. In the central primary vortex region, which is essentially in the laminar range (no viscosity), the Smagorinsky constant increases from 0.02 m/s at Re=3×10⁵ to 0.05 m/s at Re=1×10⁶, and is close to zero. The turbulence characteristics at different positions within the cavity show significant variations, resulting in corresponding changes in the Smagorinsky constant used for simulating subgrid-scale stresses. Notably, although the Smagorinsky constant is larger near the boundary, the exact values for different walls vary. The bottom wall has a larger value than the top wall, with the maximum value often appearing in the upstream region, mainly concentrated near the upstream area of the UUV region.

As the Reynolds number increases, the maximum value of the Smagorinsky constant within the cavity also increases. The maximum value at $Re=3\times10^5$ is around 0.3, reaching 0.35 at $Re=5\times10^5$, 0.4 at $Re=7\times10^5$, and 0.6 at $Re=1\times10^6$. This trend indicates that the increase in Reynolds number strengthens the turbulence within the cavity, leading to an increase in eddy viscosity, which is reflected in the rise of the

maximum value of the Smagorinsky constant. Additionally, although the overall distribution trend remains unchanged, at higher Reynolds numbers, the region with higher values of the constant expands, indicating that Reynolds number influences both the distribution range and intensity of the Smagorinsky constant within the cavity. Furthermore, as the Reynolds number increases, the turbulence within the cavity intensifies, and the region of the Smagorinsky constant tends to break up more, with the contour lines becoming more complex and the gradients steeper.

From the perspective of turbulence theory, near solid boundaries or in other laminar regions, turbulence-generated viscosity is zero, resulting in the Smagorinsky constant of zero. Closer to the boundary, the fluid is influenced by the wall, leading to complex state with strong turbulence, and a larger Smagorinsky constant is required to accurately simulate the subgrid-scale stresses and energy transfer. In the intermediate primary vortex region, which is in the laminar range and has no viscosity, the Smagorinsky constant decreases to zero (Kresta and Wood,1993). As the Reynolds number increases, the relative strength of inertial forces over viscous forces increases, and the turbulence intensity escalates. The number and activity of small-scale vortices increase, and to better simulate the subgrid-scale effects at this high turbulence intensity, the maximum value of the Smagorinsky constant increases accordingly. In conclusion, using a constant Smagorinsky value throughout the entire flow in high Reynolds number large eddy simulations is inaccurate. Since eddy viscosity differs across different regions of the flow, the corresponding Smagorinsky constant should also adapt accordingly.

The experimental findings of this study reveal the spatial correlation between the Smagorinsky constant and turbulence characteristics in high-Reynolds lid-driven cavity flows, providing the following physical basis for the optimization of subgrid-scale models: Experimental data show that C_s exhibits a non-uniform distribution approaching zero in the boundary wall region ($C_s \approx 0$ at $Re = 1 \times 10^6$). Its value increases and then decreases with increasing distance from the wall, and the peak position is significantly correlated with the spatial distribution of the local turbulent kinetic energy dissipation rate. Further analysis shows that the peak value of C_{smax} increases with Reynolds number, from 0.3 at $Re = 3 \times 10^5$ to 0.6 at $Re = 1 \times 10^6$. This suggests that subgrid models need to introduce Reynolds number-dependent dynamic scaling relationships (such as $C_s \propto Re^a$) to match the energy cascade process dominated by inertial effects. In addition, the spatial non-uniformity of the turbulent kinetic energy dissipation rate (with peak values near the wall reaching 0.6 and below 0.1 in the core region) indicates that the model must achieve a refined calibration of the dissipation term by dynamically relating C_s with local flow parameters (e.g., wall distance y⁺), particularly in the near-wall high shear region, where enhanced dissipation resolution is needed to suppress excessive damping effects, where the near-wall $v_{\rm rms}$ error reaches 0.03 m/s at $C_s = 0.18$). Notably, the low sensitivity of u_{rms} to Reynolds number in the primary vortex core (variation < 0.1 m/s) provides a validation benchmark for the robustness of the model in the inertial-dominated region. Compared to the fixed C_s model, the dynamic model reduces the error in this region to 0.01 m/s, confirming the superiority of the spatially adaptive C_s distribution. These findings

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provide experimental support for the development of partitioned dynamic subgrid models. Future research could further optimize the near-wall model parameterization by incorporating the quantitative relationship between local dissipation rate and C_s .

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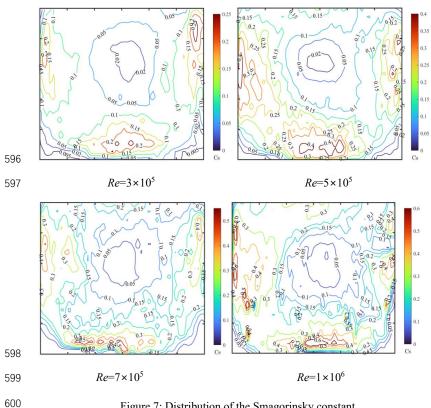


Figure 7: Distribution of the Smagorinsky constant

4. Conclusions

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This study examined water flow dynamics in a lid-driven cavity under four high Reynolds number conditions: $Re = 3 \times 10^5$, 5×10^5 , 7×10^5 , and 1×10^6 . The flow field within the cavity was measured using PIV, and RMS velocities and turbulent kinetic energy dissipation rates within the cavity were calculated. Using combination of the dimensional analysis method and large eddy PIV method, the distribution of the Smagorinsky constant within the cavity was further determined. The experimental findings yield the following key conclusions:

(1) Variation of RMS Velocity: As the Reynolds number increases, the RMS velocities (u_{rms} and v_{rms}) in the near-wall region of the cavity increase significantly, especially near the downstream wall where the RMS velocity reaches its peak. This indicates that, under high Reynolds number conditions, the turbulence intensity in the wall-adjacent regions is amplified. Specifically, when Re increases from 3×10^5 to 1×10^6 , the RMS velocity at the bottom wall increases from 0.19 m/s to 0.35 m/s, further highlighting the significant increase in turbulence intensity in the boundary layer under high Reynolds number flows.

(2) The turbulent kinetic energy dissipation rate distribution on the neutral plane of the cavity, obtained using both dimensional analysis and large eddy PIV methods, reveals higher dissipation rate near the left and right cavity walls. Moreover, under high Reynolds number conditions, the dissipation rate exhibits clear spatial non-uniformity. As the Reynolds number increases, the overall dissipation rate level rises, particularly in the near-wall region, where the dissipation of turbulent kinetic energy becomes significantly higher. For example, at $Re = 1 \times 10^6$, the peak dissipation rate near the bottom wall reaches 0.6, with its influence extending further within the cavity. These findings suggest that as the Reynolds number increases, the inertial forces dominate the

turbulent fluctuations, causing more intense dissipation of turbulent energy, which highlights the increased turbulent intensity and the spatial complexity of energy dissipation at high Reynolds numbers.

(3) Smagorinsky Constant Distribution: The Smagorinsky constant calculated from the experimental results is close to zero near the cavity walls and gradually increases with distance from the wall, reaching a maximum value before decreasing to zero in the central region of the cavity. As the Reynolds number increases, the Smagorinsky constant also rises, especially at higher Reynolds numbers, where the enhanced vortex viscosity leads to a higher peak value of the Smagorinsky constant.

Limitations: It is important to note that this study was conducted using a 2D plane for the experimental setup, and the results may not fully capture the complexities of three-dimensional flow dynamics. Testing 3D models could provide further insights into the flow behavior and energy dissipation mechanisms in the cavity, particularly at higher Reynolds numbers. This aspect will be considered as a direction for future research.

Acknowledgements

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