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## Simulation analysis of equivalent circuit model of skin-electrode impedance for transcutaneous electrical stimulation

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### ABSTRACT

For more than 50 years, transcutaneous electrical stimulation method has been used to cure the spinal cord injury, stroke or cerebral palsy. This method works by activating the excitable nerves, muscle fibers by electrical current stimulation through electrode to skin interface. Electrode to skin interface requires equivalent circuit to overcome the inability of measuring the skin resistivity directly. We have learned several previous models, which are from Lawler, Moineau and Keller and Kuhn. Unfortunately, Moineau model neglects the capacitance effect, while Lawler and Keller and Kuhn include capacitive and resistive nature of skin in their equivalent circuits. Both models consisted of only one parallel RC block. Therefore, this paper presents the simulation results of the proposed equivalent circuit model using two parallel RC circuits. Simulation of the proposed model is conducted in MATLAB 2015a and compared with two previous models using certain parameters. Results show that the proposed model obtained the impedance of 10.830 k $\Omega$  when it is simulated using 100Hz frequency, for Lawler model the impedance is 5.340 k $\Omega$  and Keller and Kuhn model the impedance obtained is 6.490 k $\Omega$ . The proposed model has the refined impedance compared with other models and is expected to deliver better electrical stimulation.

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## 1. INTRODUCTION

Wearable transcutaneous electrical stimulation (TES) or functional electrical stimulation (FES) is the method used to cure motoric injury due to stroke, spinal cord injury, or cerebral palsy, by activating excitable tissue from skin surface [1], [2]. This method has been applied in curing those diseases for > 50 years [3]. TES or FES also works by activating the nerves and muscle fibers by stimulation using electrical current pulses through two electrodes and using inter-electrode distance (IED) which attached on the skin [4].

Electrical stimulation can be applied effectively for skin restoration, diagnosis and treatment purpose, by application of artificial tactile sensory feedback in prosthetic hand [5], [6]. Application of electrical stimulation requires highly reliable electrode, sustainable, and low-cost electrode material. Textile electrode fulfills these criteria as electrode material with price at £0.16 per electrode, which also provides high measurement accuracy and reusability [7]. Textile electrode is also providing flexibility, ventilation that can lead to almost no skin irritation for long-term usage, foldability and non-hydrogel characteristics. Textile electrodes is applicable for monitoring clinical physiological signals, such as electrocardiogram (ECG), electromyography (EMG), electroencephalogram (EEG), and so forth [8].

Textile electrode or e-textile technology has been around for almost a decade. E-textile permits the injection of electrical components, such as, LED, electrodes, to lay on the fabric for it to bring additional value to fabric [9]. The e-textile will be used as for future development of this research as wearable TES device, for this stage the main concern is designing the skin model for it to interface properly with human skin. The skin model design is made based on the skin two main characteristics, such as, resistive and capacitive, applying parallel RC circuit is the way to model after these characteristics. Resistivity of skin cannot be measured directly. Therefore, equivalent network model is used to obtain the skin resistance [2]. On the other hand, skin capacitance is measurable and frequency dependent, which can be measured with a device called Corneometer CM 825 for measurement using mean frequency of 1MHz or Corneometer CM 820 for low frequency measurement (45-75 KHz) [10], [11]. The capacitance effect is useful to detect the hydration state of the skin and for biometric purpose [10]-[12]. Besides knowing the skin nature for stimulation purpose, current density in this stimulation plays a great role on the stimulation efficiency and comfort, due to the skin and electrodes in-homogeneities. High current density, which localized on the skin surface may cause discomfort and the worst case is skin burns [2].

Stimulation comfort on TES device can be improved by varying the waveform and pulse width [1], [5]. On previous research conducted by Baker *et al.*, they have tried the stimulation using six different types of waveforms such as, asymmetric balanced biphasic square waveform, symmetric biphasic square waveform, monophasic paired spike, modulated sine wave, medium sine wave and medium square wave. Results of their experiment shows that asymmetric biphasic waveform provides better comfort and does not cause any interference or stimulation on large muscle group [13], therefore it is recommended for clinical usage. Equivalent circuit models have been made to substitute the skin model interface to determine the skin impedance. In this research, we limit to three model as our literature basis. First model was made in 1959 by Lawler *et al.* using the Wheatstone bridge approach with having both capacitive and resistive components to represents the skin nature. This research shows that impedance is inversely proportional to frequency [14]. Second model made by Keller & Kuhn after the skin equivalent circuit from the skin layers [2]. Third model was made by Moineau *et al.*, but excluded capacitance effect in their equivalent circuit model [3]. Those approaches yield different results in which, for Moineau *et al.* design it simply shows no changes in resistance, whereas on Lawler *et al.* and Keller & Kuhn approach with including both resistive and capacitive nature of skin shows changes on the impedance with respect to frequency. Different equivalent circuit model has their own specialties, and also the waveform used in the stimulation may differ according to each purpose.

Electrode-skin interface is also playing an important role in electrical stimulation quality because higher impedance electrode will likely having low signal to noise (S/N) ratio, low signal amplitude and poor biological signal quality [15]. But on the other hand, higher electrode impedance may reduce discomfort in stimulation [1]. Increasing the resistivity in the electrode can be done by adding resistive gel, which act as impedance mismatch depletor. Size of electrode is affecting the current density uniformity, by applying electrode with larger contact area (70-120 cm<sup>2</sup>) may results in high current density and uniform current density, which results from the polarizable electrode characteristics, the displacement current [16]. This research is an extension work of David Tyler and Clementine Mavridis, from Manchester Metropolitan University (MMU), which our concern is in designing the more refined equivalent circuit model [17]. In this paper, the authors propose to simulate the model of Wheatstone bridge, which consists of two identical RC circuit. The RC circuit represents the resistive and capacitive nature of skin. The model will be simulated in MATLAB 2015a, with variation in resistance, capacitance and frequency. Wheatstone bridge approach is considered to be better at approximating the skin impedance, while on the other hand finding the perfect balance impedance in Wheatstone bridge is also more difficult.

## 2. HUMAN SKIN

Human skin is the largest and heaviest organ in the body which contribute 8-10% of human body mass and covers about 2 m<sup>2</sup> of our body's total area. Human skin also serves as boundaries between body and the environment such that, the vital bodily may perform under controlled physiological condition [18]-[20]. Ultraviolet (UV) light, chemicals, pathogens and mechanical injury are blocked by skin in first place [21]. Storing water and fats is also part of human skin's function and also serves as immunity to disease [22]. The main structure of human skin are epidermis, dermis and hypodermis [18]. Epidermis consist of several layers, such as, stratum corneum, stratum lucidum, stratum granulosum, stratum spinosum, stratum basale [21]. Dermis is the inner layer of supportive layer of skin, consist of vast amount of collagen and rich in blood supplies [22]. Hypodermis is the innermost layer of skin, which made up of subcutaneous fat [18].

Stratum corneum is the outermost of epidermis layer, which is the top layer of epidermis and human skin as a whole. Stratum corneum is made up of dead cell, or keratinized cell [4], [21], [22]. It is also one of the thinnest layers which has 15-20  $\mu\text{m}$  thickness only [23], [24]. Stratum corneum dominates the electronic

properties of skin when DC current applied under 10 KHz frequency [4], [23]. Resistivity of Stratum corneum is the highest amongst skin layer at about  $10^5 \Omega \text{ cm}^2$ , and conductivity of  $0.03 \mu\text{F}/\text{cm}^2$  at small current application [4], [24]. Dermis is the second main layer of human skin with thickness of 1 to 4 mm, consists of two layers, such as, papillary layer and reticular layer. Papillary layer is the upper layer of dermis, which serves as boundary to epidermis, loosely connected tissue, with large amount of nerve fibers, capillaries, water and cells. Reticular layer is the bottom part of dermis, which has denser and thicker network compare to papillary layer, houses fewer nerve fibers and capillaries [19].

### 2.1. Skin circuit model

Skin circuit model is required for electrical stimulation due to the immeasurable impedance of it [2]. Making a skin circuit model is the way to simplify our analysis. Skin circuit is modeled by an equivalent circuit, consist of RC circuit. Figure 1 shows the equivalent circuit model of skin [23].

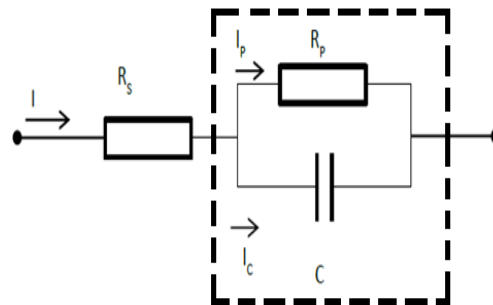


Figure 1. Skin equivalent circuit model

This skin model is the common way to represent the dielectric properties of skin and skin general response. Analysis of signal input and output from body is simplified with the modelling of this circuit. This model is the most common used for measuring the changes in impedance. In addition, this model is considered to be adequate enough to characterize the skin response [23].

In this research the parallel RC circuit will be integrated with Wheatstone bridge circuit which was invented in 1833 by Samuel H. Christie, then improved and popularized by Sir Charles Wheatstone in 1843 [25], [26]. This circuit model is intended to figure out the unknown resistance, using the defined resistance in a bridge model circuit compare with the unknown resistance [26], [27]. This is suitable for measuring skin resistance for it cannot be measured directly. Small changes in resistance can be measured by Wheatstone bridge circuit [26]. Wheatstone bridge can be used for measuring capacitance, inductance, and impedance. Wheatstone bridge circuit is used for measuring the unknown parameter for DC source. In balance state, Wheatstone bridge circuit has 0 V voltage across the bridge, therefore, when small changes occur voltage difference exists [25].

### 2.2. The previous and proposed models

In this part, we will be discussing the skin model made by Lawler *et al.*, and Keller & Kuhn, and Moineau *et al.* First, Lawler *et al.* proposed the model in 1959 Figure 2, stated that skin has both resistive and capacitive nature. They also concluded that impedance of skin will be the same as equivalent circuit in balance condition. Therefore, Lawler *et al.* come up with the model based of Wheatstone bridge for the skin to have zero voltage in balance state and construct the skin model by using parallel RC circuit, for it to have equal impedance with the skin. This skin model is connected to one of the bridge legs and opposing the electrode.

Second, Keller & Kuhn [2] proposed their comprehensive skin model with consist of the matrix and appendageal pathway. The pathways are modeled with resistor and capacitors. In their research, Keller and Kuhn obtained the skin resistivity by tuning the equivalent circuit for yielding the measured current-voltage response. Keller and Kuhn's simple lumped skin model is shown in Figure 3. Impedance formula of Lawler *et al.* model is shown in (1)

$$Z = \frac{R \cdot \left(\frac{1}{2\pi fC}\right)}{\sqrt{R^2 + \left(\frac{1}{2\pi fC}\right)^2}} \tag{1}$$

The impedance formula of the simple lumped skin model is shown in (2)

$$Z = \frac{R \cdot \left(\frac{1}{2\pi fC}\right)}{\sqrt{R^2 + \left(\frac{1}{2\pi fC}\right)^2}} + R_b + R_c \tag{2}$$

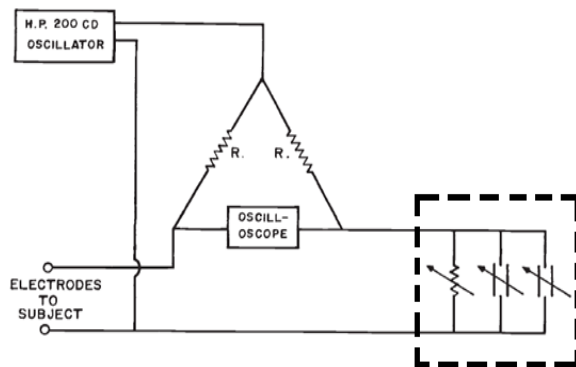


Figure 2. Lawler *et al.* skin model

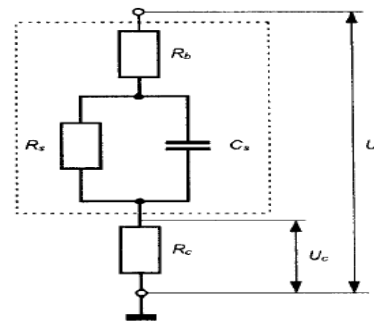


Figure 3. Simple lumped skin model

Third, Moineau *et al.* come up with the model only consisting resistive nature of skin, therefore the impedance of the circuit is by using voltage on each node of the circuit (can be solved by using Ohm’s law). The results yield without taking account any capacitance effect. In this way we obtained a distorted skin impedance value that can’t be comparable with the one of the Wheatstone bridge models [3], [9].

The proposed model is designed based on Wheatstone bridge as used in Lawler *et al.* model as shown in Figure 4. The impedance of the model is determined by the block marked with black dashed line. The impedance formula will be elaborated starting from (3) to (6), and the final formula of the impedance will be shown in (6).

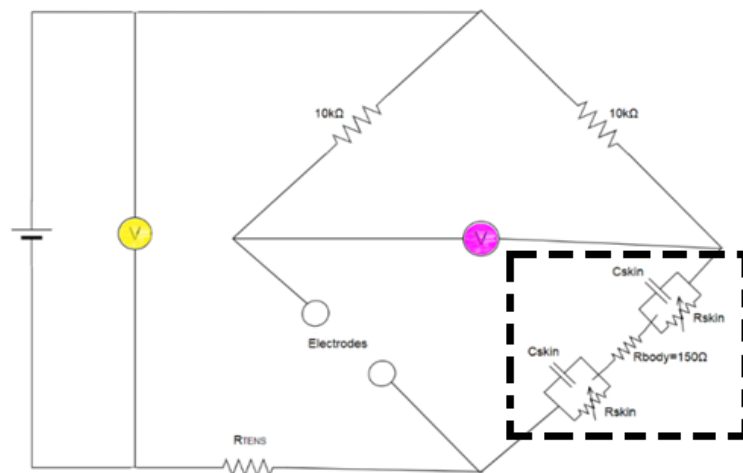


Figure 4. The proposed equivalent circuit for simulation is blocked with the black dashed line

$$Z = \frac{R_{skin} \cdot X_c}{\sqrt{R_{skin}^2 + X_c^2}} \quad (3)$$

$$X_c = \frac{1}{2\pi f C_{skin}} \quad (4)$$

$$Z = \frac{R_{skin} \cdot \left(\frac{1}{2\pi f C_{skin}}\right)}{\sqrt{R_{skin}^2 + \left(\frac{1}{2\pi f C_{skin}}\right)^2}} \quad (5)$$

Therefore, the impedance for this circuit is:

$$Z = \frac{R_{skin} \cdot \left(\frac{1}{2\pi f C_{skin}}\right)}{\sqrt{R_{skin}^2 + \left(\frac{1}{2\pi f C_{skin}}\right)^2}} + \frac{R_{skin} \cdot \left(\frac{1}{2\pi f C_{skin}}\right)}{\sqrt{R_{skin}^2 + \left(\frac{1}{2\pi f C_{skin}}\right)^2}} + R_{body} \quad (6)$$

Table 1 shows that models from Lawler *et al.* and Keller & Kuhn include capacitance and resistance nature of skin, in which the equivalent circuit can be solved for the impedance and the impedance is affected by changes in frequency. Impedance formula of both Lawler *et al.* and Keller & Kuhn models are shown in (1) to (6) and from the formula can be inferred that impedance is inversely proportional to frequency. Moineau's is the least model among those previous models and will be neglected later in our simulations.

Table 1. Performance characteristic between three previous models and the proposed model

Model/Parameter	Impedance	Capacitance	Resistance	Frequency
Lawler <i>et al.</i>	✓	✓	✓	✓
Moineau <i>et al.</i>	✗	✗	✓	✓
Keller & Kuhn	✓	✓	✓	✓
Proposed Model	✓	✓	✓	✓

### 3. SIMULATION RESULTS AND ANALYSIS

In this section, the results of simulation from the proposed model, Lawler *et al.*, and Keller & Kuhn models will be elaborated. Table 2 shows the parameters used to simulate the proposed model, Lawler *et al.* and Keller & Kuhn model, for it to be further analyzed. The frequency is chosen variably from 10 to 150 Hz. In the first, impedance vs. frequency is simulated by varying the frequency with ranging from 10 to 150 Hz. The results of simulation are shown in Figures 5-7. In Figure 5, we can see that the highest impedance of the proposed model is 19.990 K $\Omega$  and the lowest impedance of 7.911 K $\Omega$ , Lawler *et al.* model showing highest impedance of 9.877 K $\Omega$  and lowest impedance of 3.881 K $\Omega$  and Keller and Kuhn Model shows highest impedance of 11.027 K $\Omega$  and lowest impedance of 5.031 K $\Omega$ . From these results, it can be concluded that the impedance is inversely proportional to frequency.

Table 2. Simulation parameters

Models	R <sub>skin</sub> (K $\Omega$ ) (fixed)	R <sub>skin</sub> (K $\Omega$ ) (variable)	R <sub>body</sub> ( $\Omega$ )	R <sub>b</sub> ( $\Omega$ )	R <sub>c</sub> (K $\Omega$ )	C <sub>skin</sub> (nF) (variable)
Proposed Model	10	10-100	150	-	-	83-251
Lawler <i>et al.</i>	10	10-100	-	-	-	83-251
Keller and Kuhn	10	10-100	-	150	1	83-251

Then, impedance vs. resistance is simulated by varying resistance ranging from 10 K $\Omega$  to 100 K $\Omega$ , and frequency of 100 Hz. Proposed model results in the increment of 1.365 K $\Omega$  from 10 to 20 K $\Omega$ , Lawler *et al.* and Keller & Kuhn model showing increment of 0.683 K $\Omega$  from 10 to 20 K $\Omega$ , from 30 K $\Omega$  to 100 K $\Omega$  just small increment occur. The results of simulation are shown in Figure 6. Finally, impedance vs. capacitance of proposed model, Lawler *et al.* and Keller & Kuhn are simulated by varying the capacitance value ranging from 83 to 251 nF. The proposed model yields the highest impedance of 17.883 K $\Omega$  and lowest impedance of 10.860 K $\Omega$ , Lawler *et al.* model highest impedance is 8.867 K $\Omega$  and lowest impedance of 5.355 K $\Omega$ , Keller

& Kuhn model highest impedance is 10.017 KΩ and lowest impedance of 6.505 KΩ. The results are shown in Figure 7. From the results, we can conclude that capacitance is inversely proportional to impedance.

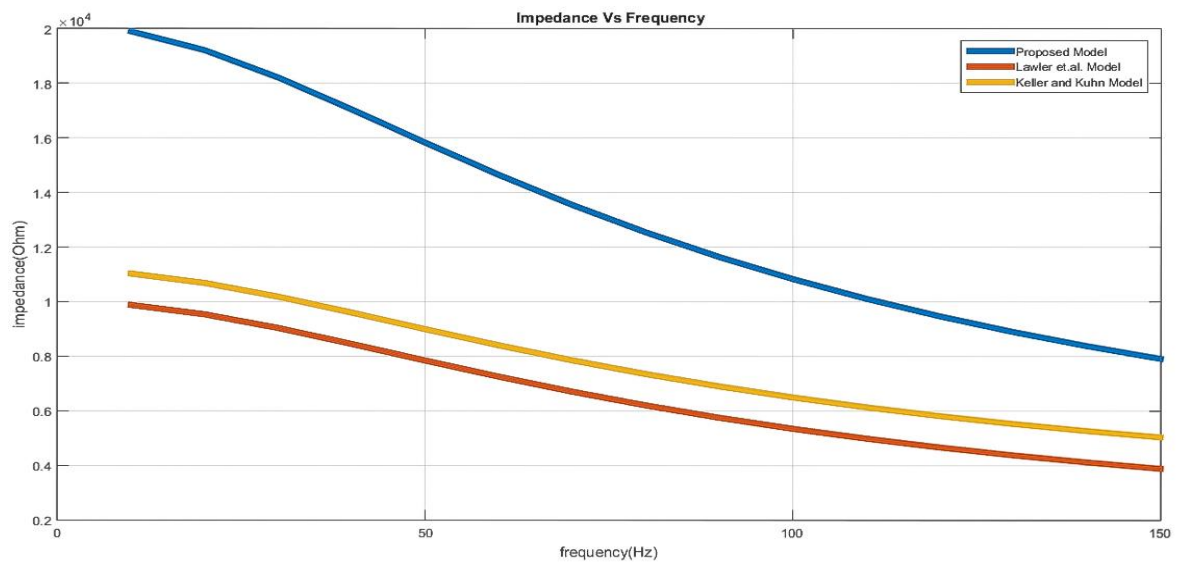


Figure 5. Impedance vs. frequency of proposed model, Lawler *et al.* and Keller and Kuhn from 10-150 Hz

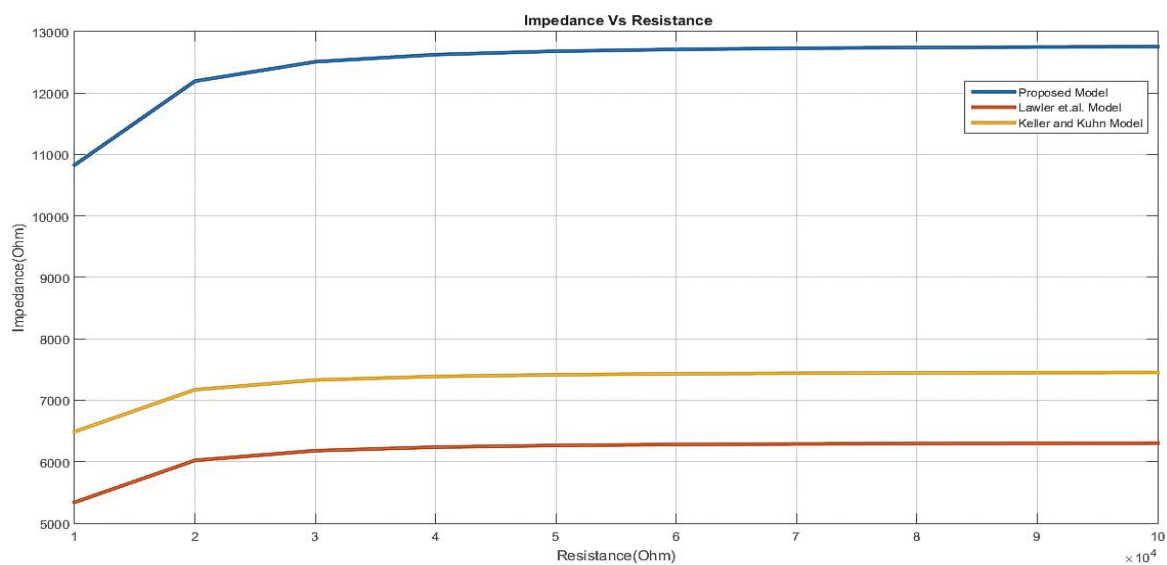


Figure 6. Impedance vs. resistance of proposed model, Lawler *et al.* and Keller and Kuhn from 10-100 K

Then, impedance vs. resistance is simulated by varying resistance ranging from 10 KΩ to 100 KΩ, and frequency of 100 Hz. Proposed model results in the increment of 1.365 KΩ from 10 to 20 KΩ, Lawler *et al.* and Keller & Kuhn model showing increment of 0.683 KΩ from 10 to 20 KΩ, from 30 KΩ to 100 KΩ just small increment occur. The results of simulation are shown in Figure 6. Finally, impedance vs. capacitance of proposed model, Lawler *et al.* and Keller & Kuhn are simulated by varying the capacitance value ranging from 83 to 251 nF. The proposed model yields the highest impedance of 17.883 KΩ and lowest impedance of 10.860 KΩ, Lawler *et al.* model highest impedance is 8.867 KΩ and lowest impedance of 5.355 KΩ, Keller & Kuhn model highest impedance is 10.017 KΩ and lowest impedance of 6.505 KΩ. The results are shown in Figure 7. From the results, we can conclude that capacitance is inversely proportional to impedance.

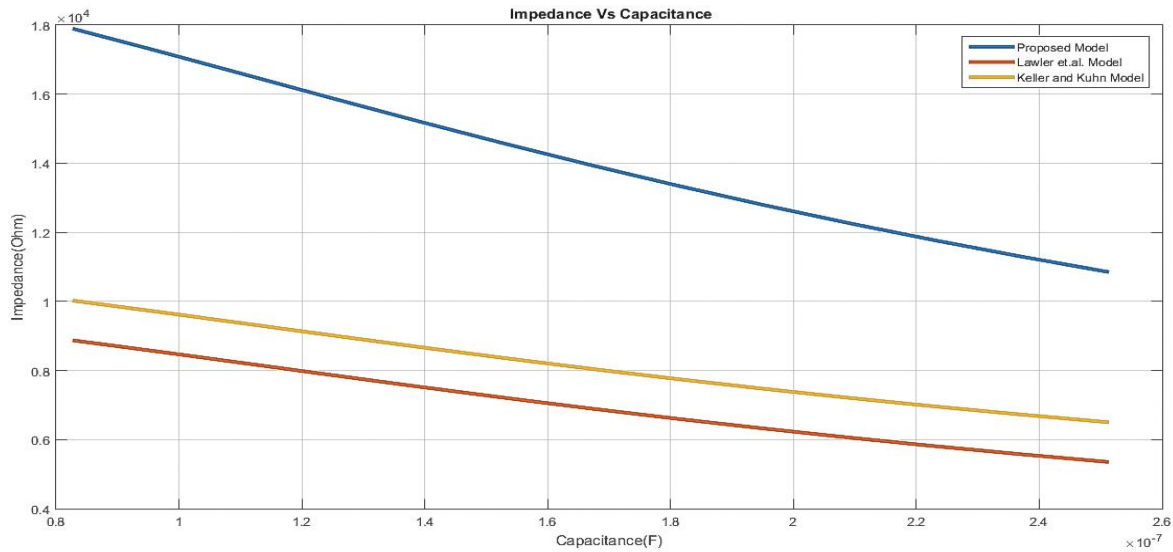


Figure 7. Impedance vs. capacitance of proposed model, Lawler *et al.* and Keller and Kuhn from 83-251 nF

In this research, the frequency is affecting the accuracy of the measurement on high frequency which can cause error due to the changing current distribution beneath electrodes surface and low frequency error due to the impedance imbalance, causing  $V \neq 0$  [27]. Low frequency impedance can be used for indicating skin burn [28]. In addition, at low frequency impedance reflects the resistive properties of extra-cellular environment. Higher frequency impedance is reflecting both resistive and capacitive properties of intra and extra-cellular environments. The overall impedance may state the clinical state of human skin [29]. The overall impedance of human tissue is in  $K\Omega$  range, measurement made on human impedance using high accuracy bioimpedance measurement system by this following set up, frequency ranging from 24 KHz to 391 KHz, excitation current of  $10 \mu A$ , and resulting  $37 K\Omega$  of impedance [30].

From the results comparison of proposed model, Lawler *et al.* and Keller & Kuhn model, by variation in frequency, resistance and capacitance, all of the impedance results showing that the proposed model shows the highest impedance, followed by Keller & Kuhn, then Lawler *et al.* The proposed model showed a refinement in terms of impedance. Having this quality, proposed model is expected to deliver better comfort stimulation.

#### 4. CONCLUSION AND FUTURE WORKS

Results yield from our simulations show that the proposed model has the highest impedance, followed by Keller & Kuhn, then Lawler *et al.* models. Therefore, the proposed model is considered to be the refinement product compared to other models and expected to deliver better comfort in electrical stimulation. For future works, adding low pass filter might be good to give a better signal to noise (S/N) ratio. Also, by modeling the equivalent circuit using Thevenin scheme, with including the parallel RC circuit and resistance.

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