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Physical Layer Security of Cooperative NOMA for IoT Networks Under I/Q Imbalance

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ABSTRACT In this paper, we investigate the reliability and security of cooperative dual-hop non-orthogonal multiple access (NOMA) for internet-of-thing (IoT) networks, in which the transceivers consider a detrimental factor of in-phase and quadrature-phase imbalance (IQI). The communication between the source and destination is accomplished through a decode-and-forward (DF) relay in the presence of an eavesdropper. In order to characterize the performance of the considered system, exact analytical expressions for the outage probability (OP) and intercept probability (IP) are derived in closed-form. Furthermore, to better understanding the performance of the considered system, we further derive the asymptotic expressions of OP in the high signal-to-noise ratio (SNR) regime and IP at the high main eavesdropping ratio (MER) region. A large number of analysis and Monte Carlo simulation results show that the existence of IQI usually increases the corresponding OP and reduces the IP, which means that reduces the reliability of the system and improves the security. In addition, the provided results provide useful insights into the trade-off between reliability and security of secure cooperative communication systems.

INDEX TERMS Cooperative communication, in-phase and quadrature-phase imbalance, Internet-of-Things, physical layer security, non-orthogonal multiple access.

I. INTRODUCTION

A. BACKGROUND

With the rapid development of the Internet of Things (IoT), the fifth generation (5G) wireless networks need to provide massive connectivity of IoT devices to meet the demand of high spectral efficiency and low latency [1]. The traditional orthogonal multiple access (OMA) technology is difficult to meeting the requirements of the 5G systems, and the non-orthogonal multiple access (NOMA) technology, as a novel multiple-access technology, which can not

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only improve the capacity and the spectral efficiency of the system well, but also the device access quantity can be increased by multiple times [2]. Compared with the OMA technology, the dominant characteristic of NOMA is to allow multiple users to share the same time, frequency and space resources by power-domain multiplexing [3]. At the transmitter, all the information is processed according to superposition coding, and then successive interference cancellation (SIC) is carried out at the receiver can decode their own information successfully [4]. In addition to enhancing the system performance, NOMA technology guarantees the fairness of multi-user by appropriate power distribution scheduling [5].

Cooperative communication is considered to be a promising technology in mobile communication networks, which can improve spectrum efficiency, power efficiency and expand network coverage [6]. NOMA based cooperative relay systems has been studied to further improve network performance [1], [7]–[12]. In [7], the authors proposed a cooperative NOMA scheme by utilizing the characteristic that users with good channel conditions can obtain the information of users with poor channel conditions in advance, which proved that the near user with better channel conditions can forward the information of the far user, acting as a relay. The reliability of cooperative NOMA system based on successive user relaying (SR) technology was investigated by deriving the outage probability (OP) and asymptotic ergodic capacity of the considered systems [8], and also proposed an optimize power allocation factor algorithm to improve the fairness between users. A buffer-aided relay selection scheme was studied by the authors in [1], which can significantly improved the throughput of the system and achieved the seamless transmission of NOMA and OMA in the relay network. In [9], the authors applied cooperative NOMA to cognitive radio network, which improved the spectral efficiency. The trade-off between energy efficiency and time delay of cooperative relay protection systems was studied in [10], where a fractional programming and control parameter-based Lyapunov optimization method was proposed to solve stochastic-based energy efficiency optimization problems. In addition, according to the way of relay nodes process the information of source nodes, it can be divided into several cooperative protocols, such as amplifying and forwarding (AF), decoding and forwarding (DF). The authors in [11] studied the outage performance of AF NOMA cooperative relay system and derived the asymptotic OP and diversity order. The effect of fading parameters and average channel coefficients on the system performance was investigated in [12] by deriving the OP and throughput of a cooperative NOMA network with DF relay over Nakagami- m fading channels.

Since the broadcast characteristic of wireless transmission, the IoT networks are more vulnerable to attack by illegal users, thus, wireless communication urgently requires a communication network with a higher degree of information security [13]. As the basis of communication networks, information security is showing unprecedented importance [14]. The conventional methods to ensure the security of wireless communication are to use encryption algorithms, which rely on complexity and time-consumption. The physical layer security (PLS) technology is based on the broadcast characteristics of wireless transmission and can realize the communication network security in the sense of information theory without key, which has received remarkable attention, e.g., see [15]–[17] and the references therein. The concept of PLS was originally proposed by Wyner in [15]. Then, the authors investigated the secrecy performance of a cooperative system with DF scheme over Rician fading channels in [16]. The secrecy performance of systems with multiple

eavesdroppers under colluding and non-colluding scenarios was studied in [17], where the channel state information (CSI) of the considered systems is outdated.

Recently, adopting PLS in cooperative NOMA systems has also attracted some significant research attentions. In [18], the authors derived the closed expressions of secure outage probability (SOP) and strictly positive secrecy capacity (SPSC) of cooperative NOMA system under AF and DF relay modes, which verified that the secure performance of the system can be improved by using the optimal power allocation parameters. In [19], a new NOMA cooperative jamming scheme was proposed to improve the security of the communication system. The authors in [20] evaluated the security and reliability of downlink cooperative NOMA in cognitive networks. In view of the multiple-relay assisted NOMA system, there are three relay selection schemes, i.e., optimal single relay selection (OSRS) scheme, two-step single relay selection (TSRS) scheme and optimal dual relay selection (ODRS) scheme were proposed to studied the secrecy outage performance of the considered system [21]. In order to improve the secure performance of the system, the authors proposed a cooperative jamming strategy for confuse relays in [21], and verified that the transmission power and fading parameters have a certain impact on the secure performance. As a further advance, a novel two-stage secure relay selection (TSSRS) with NOMA was proposed to improve the capacity between the source and destination in [22], so as to protect the communication link from eavesdropping. In addition, information transmission security can also be achieved by adding artificial noise [23]. Therefore, the secrecy performance of the multiple-antenna NOMA systems was enhanced by using the artificial noise technology in [24].

A common characteristic of the aforementioned research works is that they all consider the ideal RF front-end, and ignored the related defects of the RF front-end. However, low-cost, low-power, and small-size direct-conversion transceivers inevitably suffer from RF front-end related imperfections in practical communication systems due to the mismatch of analog components and the non-ideal transceiver manufacturing, which limit the overall system performance [25]. A typical example of these defects is the in-phase and quadrature-phase imbalance (IQI). This imbalance refers to the amplitude and phase mismatch between the in-phase (I) and quadrature-phase (Q) branches of the transceiver, which leads to imperfection of image suppression and ultimately to the degradation to the performance of the communication systems [26]. With perfect I/Q matching, the transceiver's I and Q branches will have the same amplitude and 90° phase shift [27]. However, in actual applications, due to the unsatisfactory analog components used in the transceiver, IQI always exists in the direct-conversion transceiver.

In this context, several research works analyzed the performance of system with IQI [28]–[31]. More specifically, the outage performance of the AF cooperative systems under

IQI was studied by deriving the exact closed-form analytical expressions of the OP and ergodic capacity for the considered system in [28]. The authors of [29] investigated the impact of RF front-end IQI on the performance of based on space time block coding (STBC)-orthogonal frequency division multiplexing (OFDM) systems. Then, the impact of IQI and phase noise (PHN) on the beamforming of OFDM direct-conversion transceivers was analyzed in [30]. A novel relay authentication scheme was proposed in [31] to enhance the security of the cooperation systems by utilizing the presence of IQI at the transceivers. However, only a few works in the open literature studied the impact of IQI on the performance of NOMA-based wireless communication systems [32], [33]. Specifically, the authors discussed the OP of the single-carrier and multi-carrier and which proved that IQI would have a different effect on each user of NOMA-based system in the presence of IQI [32]. The impact of IQI on cooperative NOMA systems in [33] was studied by deriving the OP and ergodic sum rate (ESR).

B. MOTIVATIONS AND CONTRIBUTION

Although there are a large amount of research works on cooperative NOMA systems, PLS and IQI, to the best of our knowledge, there is no relevant research work that discussed the security and reliability based on the cooperative NOMA system in the presence of IQI. In the literature [32], [33], the authors studied the impact of IQI on the performance of the NOMA system, but the possibility of eavesdropping on the communication link was not considered due to the time-varying nature of the wireless channel. Motivated by the aforementioned discussions, in this work, we study the secure performance of NOMA systems in terms of OP and IP in the presence of IQI. The main contributions to this paper are summarized as follows:

- Considering IQI at both the transmitter (TX) and receiver (RX), we investigate the reliability and security of the cooperative NOMA networks by deriving the exact closed-form analytical expressions for OP and IP of the far and near users.
- In order to get deeper insights of the reliability for the considered system, the asymptotic behaviors for the OP in the high signal-to-noise ratio (SNR) region are derived.
- By introducing the main-to-eavesdropper ratio (MER), we derive the asymptotic IP in the high MER region. We demonstrate that there is a trade-off between the outage and intercept performance, and provide useful insights.

C. ORGANIZATION AND NOTATIONS

The rest of this paper is organized as follows: Section II presents the cooperative NOMA system under consideration and channel model in the presence of IQI. In Section III, we derive the exact closed-form analytical expressions of OP and IP for the considered system in order to investigate the reliability and security. Section IV provides the respective

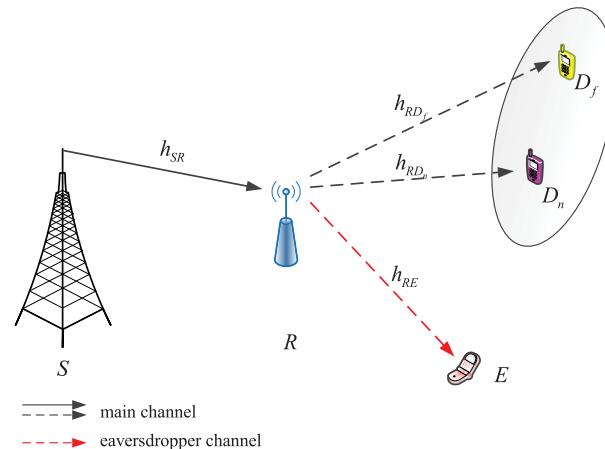


FIGURE 1. System model.

numerical results and performance evaluation discussions. Finally, conclusions of this paper is given in Section V.

Notations: In this paper, the main notations are shown as follows: the $E \{ \cdot \}$ and $|\cdot|$ denote the expectation and absolute operations, respectively. A complex Gaussian random variable with mean μ and variance σ^2 reads as $\mathcal{CN} \{ \mu, \sigma^2 \}$. $(\cdot)^*$ denotes conjugation. $\Re \{ x \}$ and $\Im \{ x \}$ represent the real and imaginary parts of x , respectively. Notation $Pr(\cdot)$ is the probability, while $f_x(\cdot)$ and $F_x(\cdot)$ are the probability density function (PDF) and the cumulative distribution function (CDF) of a random variable, respectively.

II. SYSTEM MODEL AND FADING MODEL

A. SYSTEM MODEL

We consider a downlink dual-hop underlay cooperative NOMA DF relay network shown in Fig. 1, which consists of one base station (BS) operating as the source (S), one relay (R), two legitimate destination nodes namely, the far user (D_f) and near user (D_n), and one eavesdropper (E), all nodes are equipped with a single antenna and have perfect CSI. On the premise of generality, we assume that there is no direct connection between S and destination, i.e., due to the large objects or heavy shadow, the source transmits the information to the destination node by the relay node. In addition, the E is only considered in the context of the R, it can intercept data from R.

Data transmission takes place in two phases, in the first phase, S transmits its information to R; in the second phase, R decodes and forwards the received signal to D and E. In this paper, we consider the existence of IQI on both the TX and the RX. In general, IQI is modeled as phase and/or amplitude imbalance between the transceiver I and Q signal paths. Therefore, the time-domain baseband representation of the IQI impaired signal is represented as [34]

$$x_{IQI} = \mu_{t/r}x + \nu_{t/r}x^*, \tag{1}$$

where x is the baseband transmitted signal under perfect TX/RX IQI matching, x^* indicates the mirror signal after being affected by IQI. In addition, the IQI coefficients $\mu_{t/r}$

and $v_{t/r}$ are given by [35]

$$\mu_t = \frac{1}{2} (1 + \zeta_t \exp(j\phi_t)), \quad (2)$$

$$v_t = \frac{1}{2} (1 - \zeta_t \exp(-j\phi_t)), \quad (3)$$

$$\mu_r = \frac{1}{2} (1 + \zeta_r \exp(-j\phi_r)), \quad (4)$$

$$v_r = \frac{1}{2} (1 - \zeta_r \exp(j\phi_r)), \quad (5)$$

where $\zeta_{t/r}$ and $\phi_{t/r}$ denote the TX/RX amplitude and phase mismatch levels, respectively. It is noted that for ideal IQI, there parameters are $\zeta_t = \zeta_r = 1$, and $\phi_t = \phi_r = 0^\circ$; in this case, we will get $\mu_t = \mu_r = 1$, $v_t = v_r = 0$.

1) *The first phase:* We assume an ideal RF front end, the transmitted signal at S represented as $x_s = \sqrt{a_1 P_s} x_1 + \sqrt{a_2 P_s} x_2$ with $E(|x_1|^2) = E(|x_2|^2) = 1$, where x_1 and x_2 are the transmitted signals from S for D_f and D_n , respectively; P_s is the transmit power at S ; a_1 and a_2 are the power allocation coefficients with $a_1 + a_2 = 1$ and $a_1 > a_2$. We consider the existence of IQI on both the TX and the RF front-end, the received signal at the R is given by

$$y_R = \mu_{r_1} [h_1 (\mu_{t_1} x_s + v_{t_1} (x_s)^*) + n_0] + v_{r_1} [h_1 (\mu_{t_1} x_s + v_{t_1} (x_s)^*) + n_0]^*, \quad (6)$$

where h_1 is the small-scale fading coefficient between S and R , $n_0 \sim \mathcal{CN}(0, N_0)$ represents the complex additive white Gaussian noise (AWGN); μ_{t_1} and v_{t_1} represent the amplitude and phase parameters of the IQI at the transmitter S , respectively; μ_{r_1} and v_{r_1} are defined as the amplitude and phase parameters of the IQI at the transmitter R .

According to the NOMA protocol, SIC is applied at R to decode D_f 's signal x_1 first and then cancel its component from the received signal to detect D_n 's signal x_2 . Thus, the received signal-to-interference-plus-noise ratio (SINR) of the signals x_1 and x_2 at R can be expressed as

$$\gamma_{SR}^{x_1} = \frac{a_1 \rho_1 \gamma_1 A_1}{a_2 \rho_1 \gamma_1 A_1 + \rho_1 \gamma_1 B_1 + C_1}, \quad (7)$$

$$\gamma_{SR}^{x_2} = \frac{a_2 \rho_1 \gamma_1 A_1}{a_1 \rho_1 \gamma_1 D_1 + \rho_1 \gamma_1 B_1 + C_1}, \quad (8)$$

where $A_1 = |\mu_{r_1} \mu_{t_1} + v_{r_1} v_{t_1}^*|^2$, $B_1 = |\mu_{r_1} v_{t_1} + v_{r_1} \mu_{t_1}^*|^2$, $C_1 = |\mu_{r_1}|^2 + |v_{r_1}|^2$, $D_1 = |(\mu_{r_1} \mu_{t_1} - 1) + v_{r_1} v_{t_1}^*|^2$, $\rho_1 = |h_1|^2$. In addition, we define $\gamma_1 = P_s/N_0$ as the transmit SNR at S . $A_1 = |\mu_{r_1} \mu_{t_1} + v_{r_1} v_{t_1}^*|^2 = |\mu_{r_1} \mu_{t_1}|^2 + |v_{r_1} v_{t_1}^*|^2 + 2\Re\{\mu_{r_1} \mu_{t_1} v_{r_1} v_{t_1}^*\}$, whereas due to the inequality [36]

$$2\Re\{\mu_{r_1} \mu_{t_1} v_{r_1} v_{t_1}^*\} \ll |\mu_{r_1} \mu_{t_1}|^2 + |v_{r_1} v_{t_1}^*|^2, \quad (9)$$

so A_1 can be accurately represented as $A_1 \approx |\mu_{r_1} \mu_{t_1}|^2 + |v_{r_1} v_{t_1}^*|^2$, in the same way $D_1 \approx |(\mu_{r_1} \mu_{t_1} - 1)|^2 + |v_{r_1} v_{t_1}^*|^2$.

2) *The second phase:* Use the DF protocol at R , the information transmitted from R is $x_R = \sqrt{b_1 P_R} x_1 + \sqrt{b_2 P_R} x_2$, where b_1 and b_2 are the power allocation coefficients with

$b_1 + b_2 = 1$ and $b_1 > b_2$, P_R is the transmit power at R . Similarly, we consider that IQI exists at both the relay and the receiver, therefore, the received signals at D_f , D_n , and E can be respectively expressed as

$$y_{D_f} = \mu_{r_2} [h_2 (\mu_{t_2} x_R + v_{t_2} (x_R)^*) + n_0] + v_{r_2} [h_2 (\mu_{t_2} x_R + v_{t_2} (x_R)^*) + n_0]^*, \quad (10)$$

$$y_{D_n} = \mu_{r_3} [h_3 (\mu_{t_2} x_R + v_{t_2} (x_R)^*) + n_0] + v_{r_3} [h_3 (\mu_{t_2} x_R + v_{t_2} (x_R)^*) + n_0]^*, \quad (11)$$

$$y_E = \mu_{r_4} [h_4 (\mu_{t_2} x_R + v_{t_2} (x_R)^*) + n_0] + v_{r_4} [h_4 (\mu_{t_2} x_R + v_{t_2} (x_R)^*) + n_0]^*, \quad (12)$$

where h_2, h_3, h_4 are the channel coefficient between the $R \rightarrow D_f, R \rightarrow D_n$ and $R \rightarrow E$, respectively; μ_{t_2} and v_{t_2} represent the amplitude and phase parameters of the IQI at the transmitter R , respectively; μ_{r_2} and v_{r_2}, μ_{r_3} and v_{r_3}, μ_{r_4} and v_{r_4} are represented as IQI parameters at receiver D_f, D_n and E , respectively. The signals x_1 and x_2 are decoded and forwarded to D_f and D_n by R , respectively. The received SINR for D_f to decode the signal x_1 is given by

$$\gamma_{RD_f}^{x_1} = \frac{b_1 \rho_2 \gamma_2 A_2}{b_2 \rho_2 \gamma_2 A_2 + \rho_2 \gamma_2 B_2 + C_2}, \quad (13)$$

where $A_i = |\mu_{r_i} \mu_{t_2} + v_{r_i} v_{t_2}^*|^2 \approx |\mu_{r_i} \mu_{t_2}|^2 + |v_{r_i} v_{t_2}^*|^2$, $B_i = |\mu_{r_i} v_{t_2} + v_{r_i} \mu_{t_2}^*|^2 \approx |\mu_{r_i} v_{t_2}|^2 + |v_{r_i} \mu_{t_2}^*|^2$, $C_i = |\mu_{r_i}|^2 + |v_{r_i}|^2$, $i \in (2, 3, 4)$, $\rho_i = |h_i|^2$. In addition, we define $\gamma_2 = P_R/N_0$ is the transmit average SNR at R .

Similarly, considering the perfect CSI of the D_n , the D_n will perform the SIC to cancel the interference caused by the D_f , which is generated under the assumption of perfect cancellation. Therefore, the received SINR at D_n can be given as

$$\gamma_{RD_n}^{x_1} = \frac{b_1 \rho_3 \gamma_2 A_3}{b_2 \rho_3 \gamma_2 A_3 + \rho_3 \gamma_2 B_3 + C_3}, \quad (14)$$

$$\gamma_{RD_n}^{x_2} = \frac{b_2 \rho_3 \gamma_2 A_3}{b_1 \rho_3 \gamma_2 D_2 + \rho_3 \gamma_2 B_3 + C_3}, \quad (15)$$

where $D_2 = |(\mu_{r_3} \mu_{t_2} - 1) + v_{r_3} v_{t_2}^*|^2 \approx |\mu_{r_3} \mu_{t_2} - 1|^2 + |v_{r_3} v_{t_2}^*|^2$.

According to the NOMA principle, E successfully eliminates the signal of D_f with SIC when the D_n 's signal is eavesdropped and treats the signal of D_n as noise when the D_f 's signal is eavesdropped. Thus, we can obtain

$$\gamma_E^{x_1} = \frac{b_1 \rho_4 \gamma_2 A_4}{b_2 \rho_4 \gamma_2 A_4 + \rho_4 \gamma_2 B_4 + C_4}, \quad (16)$$

$$\gamma_E^{x_2} = \frac{b_2 \rho_4 \gamma_2 A_4}{b_1 \rho_4 \gamma_2 D_3 + \rho_4 \gamma_2 B_4 + C_4}, \quad (17)$$

where $D_3 = |(\mu_{r_4} \mu_{t_2} - 1) + v_{r_4} v_{t_2}^*|^2 \approx |\mu_{r_4} \mu_{t_2} - 1|^2 + |v_{r_4} v_{t_2}^*|^2$.

B. STATISTICAL CHARACTERISTICS

In this paper, we assume that all channels experience Rayleigh fading [37]. ρ_i follows Rayleigh distribution with the PDF and CDF can be expressed as

$$f_{\rho_i}(x) = \frac{1}{\beta_i} e^{-\frac{x}{\beta_i}}, \tag{18}$$

$$F_{\rho_i}(x) = 1 - e^{-\frac{x}{\beta_i}}, \tag{19}$$

where $\beta_i = E[\rho_i]$ is the corresponding channel variance.

III. PERFORMANCE ANALYSES OF THE OUTAGE PROBABILITY AND INTERCEPT PROBABILITY

In this section, we investigate the reliability and security of the system by deriving the exact closed-form analytical expressions of the OP and IP. To obtain deeper insights, the asymptotic behaviors for the OP and IP are analyzed.

A. OUTAGE PROBABILITY ANALYSIS

1) Outage Probability for D_f

The outage event occurs at D_f when: i) R cannot successfully decode x_1 or x_2 and ii) R successfully decode x_1 and x_2 while D_f cannot decode its signal. Therefore, the OP at D_f can be represented as

$$P_{out}^{D_f} = 1 - \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{th,f}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{th,n}}, \frac{\gamma_{x_1}^{RD_f}}{\gamma_{th,f}}\right) > 1\right), \tag{20}$$

where $\gamma_{th,f}$ is the target rate of D_f .

Theorem 1: For Rayleigh fading channels, the exact closed-form expression for the OP of D_f is given by

$$P_{out}^{D_f} = 1 - e^{-\left(\frac{M_3}{\beta_1} + \frac{M_4}{\beta_2}\right)}, \tag{21}$$

where

$$M_1 = \frac{C_1 \gamma_{th,f}}{\gamma_1(a_1 A_1 - a_2 A_1 \gamma_{th,f} - B_1 \gamma_{th,f})},$$

$$M_2 = \frac{C_1 \gamma_{th,n}}{\gamma_1(a_2 A_1 - a_1 D_1 \gamma_{th,n} - B_1 \gamma_{th,n})},$$

$$M_4 = \frac{C_2 \gamma_{th,f}}{\gamma_2(b_1 A_2 - b_2 A_2 \gamma_{th,f} - B_2 \gamma_{th,f})},$$

$$M_3 = \max(M_1, M_2).$$

Moreover, (21) applies to the simultaneous establishment of

$$0 < \gamma_{th,f} < \min\left(\frac{a_1 A_1}{a_2 A_1 + B_1}, \frac{b_1 A_2}{b_2 A_2 + B_2}\right), \tag{22}$$

and

$$0 < \gamma_{th,n} < \frac{a_2 A_1}{a_1 D_1 + B_1}, \tag{23}$$

otherwise $P_{out}^{D_f} = 1$.

2) Outage Probability for D_n

The outage event occurs at D_n when: i) R can not successfully decode x_1 and x_2 ; ii) R decode x_1 and x_2 while D_n can not decode the signals. Therefore, the OP at D_n can be expressed as

$$P_{out}^{D_n} = \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{th,f}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{th,n}}\right) < 1\right)$$

$$+ \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{th,f}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{th,n}}\right) \geq 1, \min\left(\frac{\gamma_{x_1}^{RD_n}}{\gamma_{th,f}}, \frac{\gamma_{x_2}^{RD_n}}{\gamma_{th,n}}\right) < 1\right). \tag{24}$$

where $\gamma_{th,n}$ is the target rate of D_n .

Theorem 2: For Rayleigh fading channels, the exact closed-form expression for the OP of D_n is given by

$$P_{out}^{D_n} = 1 - e^{-\left(\frac{M_5}{\beta_1} + \frac{M_7}{\beta_3}\right)}, \tag{25}$$

where

$$M_5 = \frac{C_3 \gamma_{th,f}}{\gamma_2(b_1 A_3 - b_2 A_3 \gamma_{th,f} - B_3 \gamma_{th,f})},$$

$$M_6 = \frac{C_3 \gamma_{th,n}}{\gamma_2(b_2 A_3 - b_1 D_2 \gamma_{th,n} - B_3 \gamma_{th,n})},$$

$$M_7 = \max(M_5, M_6).$$

Note that all the conditions that make (25) happens if

$$0 < \gamma_{th,f} < \min\left(\frac{a_1 A_1}{a_2 A_1 + B_1}, \frac{b_1 A_3}{b_2 A_3 + B_3}\right), \tag{26}$$

and

$$0 < \gamma_{th,n} < \min\left(\frac{a_2 A_1}{a_1 D_1 + B_1}, \frac{b_2 A_3}{b_1 D_2 + B_3}\right), \tag{27}$$

otherwise $P_{out}^{D_n} = 1$.

Proof: See Appendix A. □

B. INTERCEPT PROBABILITY ANALYSIS

In this subsection, we analyze the secrecy performance of the cooperative NOMA system in the presence of IQI in terms of IP. The eavesdropper can successfully intercept the information of the legitimate user D_f or D_n only if the information of x_1 and x_2 is correctly decoded at R .

1) Intercept Probability for D_f

User D_f will be intercept if E can successfully wiretap D_f 's signal. Then, the IP of D_f by E can be expressed as

$$P_{int}^{D_f} = \Pr\left(\gamma_{x_1}^{SR} > \gamma_{th,f}, \gamma_{x_2}^{SR} > \gamma_{th,n}, \gamma_{x_1}^{RE} > \gamma_{thE_1}\right), \tag{28}$$

where γ_{thE_1} denotes the secrecy SNR threshold of D_f . The following theorem explores the secure performance in term of IP over Rayleigh fading channels with IQI.

Theorem 3: For Rayleigh fading channels, the exact closed-form expression for the IP of D_f is given by

$$P_{int}^{D_f} = e^{-\left(\frac{M_3}{\beta_1} + \frac{N_1}{\beta_4}\right)}, \tag{29}$$

where $N_1 = \frac{C_4 \gamma_{thE_1}}{\gamma_2(b_1 A_4 - b_2 A_4 \gamma_{thE_1} - B_4 \gamma_{thE_1})}$ with $0 < \gamma_{th,f} < \frac{a_1 A_1}{a_2 A_1 + B_1}$, $0 < \gamma_{th,n} < \frac{a_2 A_1}{a_1 D_1 + B_1}$ and $0 < \gamma_{thE_1} < \frac{b_1 A_4}{b_2 A_4 + B_4}$, otherwise $P_{int}^{D_f} = 0$.

2) Intercept Probability for D_n

$$P_{int}^{D_n} = \Pr\left(\gamma_{x_1}^{SR} > \gamma_{th,f}, \gamma_{x_2}^{SR} > \gamma_{th,n}, \gamma_{x_2}^{RE} > \gamma_{thE_2}\right), \tag{30}$$

where γ_{thE_2} denotes the secrecy SNR threshold of D_n . The following theorem explores the secure performance in term of IP over Rayleigh fading channels with IQI.

Theorem 4: For Rayleigh fading channels, the exact closed-form expression for the IP of D_n is given by

$$P_{int}^{D_n} = e^{-\left(\frac{M_3}{\beta_1} + \frac{N_2}{\beta_4}\right)}, \quad (31)$$

where $N_2 = \frac{C_4 \gamma_{th} E_2}{\gamma_2 (b_2 A_4 - b_1 D_3 \gamma_{th} E_2 - B_4 \gamma_{th} E_2)}$ with $0 < \gamma_{thf} < \frac{a_1 A_1}{a_2 A_1 + B_1}$, $0 < \gamma_{thn} < \frac{a_2 A_1}{a_1 D_1 + B_1}$ and $0 < \gamma_{thE_1} < \frac{b_2 A_4}{b_1 D_3 + B_4}$, otherwise $P_{int}^{D_n} = 0$.

Proof: See Appendix B. □

C. ASYMPTOTIC ANALYSIS

In order to obtain further insights, we focus on the asymptotic analysis in terms of OP and IP.

1) Outage Probability

At high SNRs, the CDF of the channel gain ρ_i can be expressed as

$$F_{\rho_i}^\infty(x) \approx \frac{x}{\beta_i}, \quad (32)$$

Corollary 1: At high SNRs, the asymptotic expression for the OP of D_f in cooperative NOMA system is given as

$$\begin{aligned} P_{out}^{D_f, \infty} &= F_{\rho_1}^\infty(M_3) + F_{\rho_2}^\infty(M_4) - F_{\rho_1}^\infty(M_3) F_{\rho_2}^\infty(M_4) \\ &= \frac{M_3}{\beta_1} + \frac{M_4}{\beta_2} - \frac{M_3 M_4}{\beta_1 \beta_2}. \end{aligned} \quad (33)$$

Corollary 2: At high SNRs, the asymptotic expression for the OP of D_n in cooperative NOMA system is given as

$$\begin{aligned} P_{out}^{D_n, \infty} &= F_{\rho_1}^\infty(M_3) + F_{\rho_2}^\infty(M_7) - F_{\rho_1}^\infty(M_3) F_{\rho_2}^\infty(M_7) \\ &= \frac{M_3}{\beta_1} + \frac{M_7}{\beta_3} - \frac{M_3 M_7}{\beta_1 \beta_3}. \end{aligned} \quad (34)$$

Remark 1: From **Corollary 1** and **Corollary 2**, we can obtain that the asymptotic outage performance of the D_f and D_n changes with the average transmit SNR.

2) Intercept Probability

Corollary 3: We taking the MER as $\beta_{me} = \beta_1/\beta_4$. According to $\exp(-x) \approx 1-x$, at high MER, the asymptotic expression for the IP of D_f in cooperative NOMA system is given as

$$\begin{aligned} P_{int}^{D_f, \infty} &= e^{-\frac{1}{\beta_4} \left(\frac{M_3}{\beta_{me}} + N_1\right)} \\ &\approx e^{-\frac{N_1}{\beta_4} \left(1 - \frac{M_3}{\beta_4 \beta_{me}}\right)}. \end{aligned} \quad (35)$$

Corollary 4: At high MER, the asymptotic expression for the IP of D_n in cooperative NOMA system is given as

$$\begin{aligned} P_{int}^{D_n, \infty} &= e^{-\frac{1}{\beta_4} \left(\frac{M_3}{\beta_{me}} + N_2\right)} \\ &\approx e^{-\frac{N_2}{\beta_4} \left(1 - \frac{M_3}{\beta_4 \beta_{me}}\right)}. \end{aligned} \quad (36)$$

IV. NUMERICAL RESULTS

In this section, some numerical results are given to validate the correctness of theoretical analysis of the OP and IP. The results are then verified using Monte Carlo simulations with 10^7 iterations. Unless otherwise specified, we have used the following parameter values: $N = 1$, $\gamma_{thf} = 1$, $\gamma_{thn} = 3$,

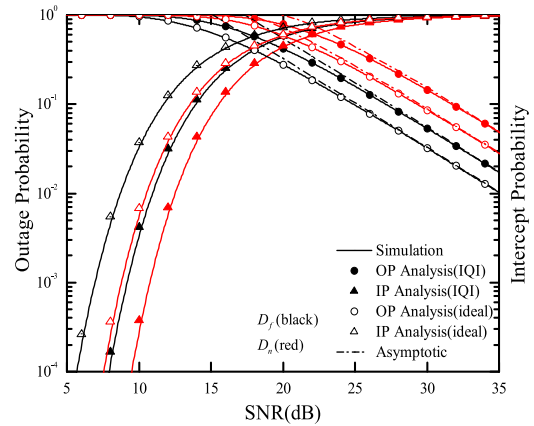


FIGURE 2. OP and IP versus the transmit SNR.

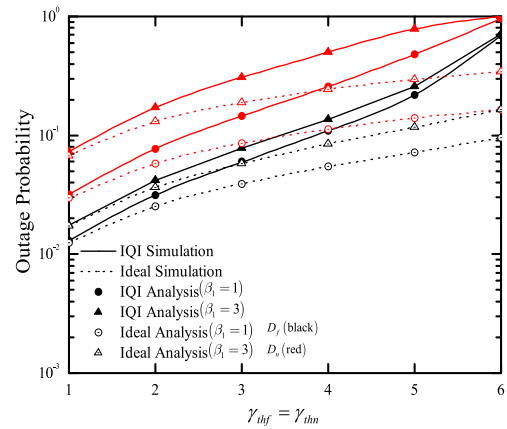


FIGURE 3. OP versus the target rate ($\gamma_{thf} = \gamma_{thn}$) for different β_1 .

$\gamma_{thE_1} = \gamma_{thE_2} = 2$, the power allocation coefficients are $a_1 = b_1 = 0.9$ and $a_2 = b_2 = 0.1$, the channel fading parameters are $\beta_1 = 1$, $\beta_2 = \beta_3 = 0.5$, $\beta_4 = 1$. Furthermore, the IQI parameters are set as $\zeta_t = \zeta_r = 1.1$, $\phi_t = \phi_r = 5^\circ$, for the ideal RF front-end $\zeta_t = \zeta_r = 1$, $\phi_t = \phi_r = 0^\circ$.

Fig. 2 shows the OP and IP of cooperative NOMA network versus the transmit SNR under the ideal and IQI conditions. These curves represent the OP, IP, and asymptotic analysis obtained from (21), (25), (29), (31) and (33), (34). From this figure, we can see that the theoretical analysis matches precisely with the Monte Carlo simulation results over the entire SNRs region, which verifies the correctness of our analysis. These results also indicate that the outage performance of each user under ideal conditions outperforms that of the IQI conditions, and the IP under ideal conditions is greater than that under IQI conditions, which means that the presence of IQI can reduce the reliability and improve the security of the system. In addition, there is a trade-off between reliability and security, which implies that performance optimization is required.

Fig. 3 demonstrates the OP versus target rate for different fading parameters ($\beta_1 = 1, 3$) under ideal and IQI conditions. In this simulation, we set $SNR = 30\text{dB}$ and assume that the far user and near user have the same target rate. From the Fig. 3, we can see that the user's OP increases with

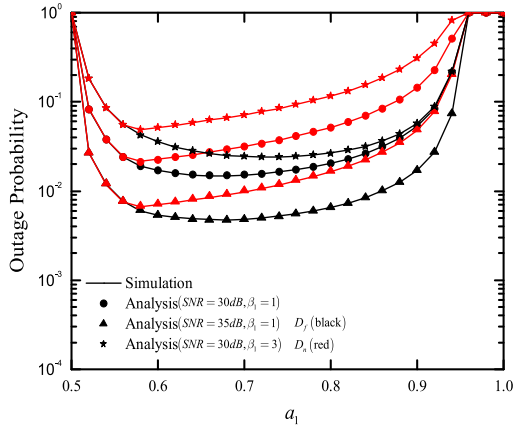


FIGURE 4. OP versus a_1 for different transmit SNR and β_1 .

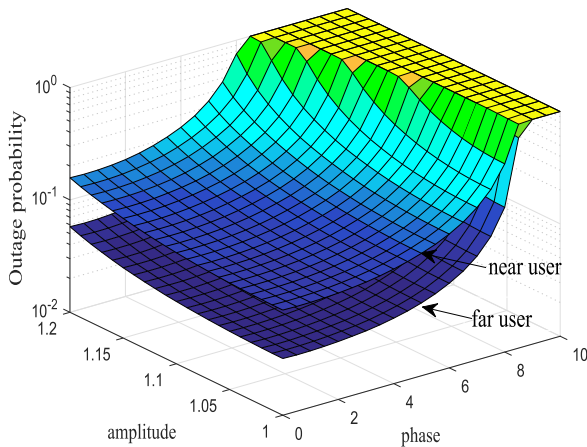


FIGURE 5. OP versus amplitude mismatch ($\zeta_t = \zeta_r$) and phase mismatch ($\phi_t = \phi_r$).

the increase of γ_{thf} . When the channel fading parameter β_1 increases, the reliability of the considered system increases. Furthermore, it is shown that IQI affects D_n more severely than D_f , which is due to the fact that D_n is also subjected to interference from D_f after the SIC is executed, which leads to the increase of OP.

Fig. 4 presents the OP versus the power allocation ratio a_1 for different transmit SNR values and fading parameters β_1 . First of all, we can see that D_f is in an outage when $\gamma_{thf} > \min\{a_1A_1/(a_2A_1 + B_1), b_1A_2/(b_2A_2 + B_2)\}$ or $\gamma_{thn} > a_2A_1/(a_1D_1 + B_1)$, D_n is in an outage when $\gamma_{thf} > \min\{a_1A_1/(a_2A_1 + B_1), b_1A_3/(b_2A_3 + B_3)\}$ or $\gamma_{thn} > \min\{a_2A_1/(a_1D_1 + B_1), b_2A_3/(b_1D_2 + B_3)\}$. In other cases, these curves first decrease and then increase as a_1 increases. As a matter of fact, the larger a_1 is, the easier it becomes to decode x_1 , and the decoding of x_2 becomes more difficult, hence the combination of x_1 and x_2 causes a change in the curves. Furthermore, we can also see that no matter how SNR and β_1 change, D_n always has an optimal performance value when $a_1 \approx 0.57$, while the change of SNR has a slight effect on the optimal value of D_f , and the change of β_1 has great influence on the optimal value of D_f .

Fig. 5 depicts the OP of the far and near users versus the amplitude mismatch ($\zeta_t = \zeta_r$) and phase mismatch

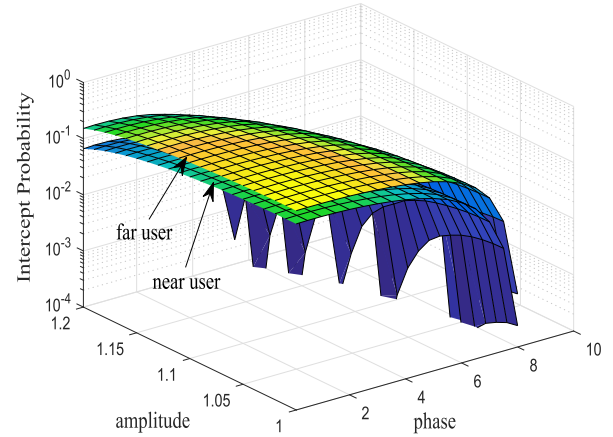


FIGURE 6. IP versus amplitude mismatch ($\zeta_t = \zeta_r$) and phase mismatch ($\phi_t = \phi_r$).

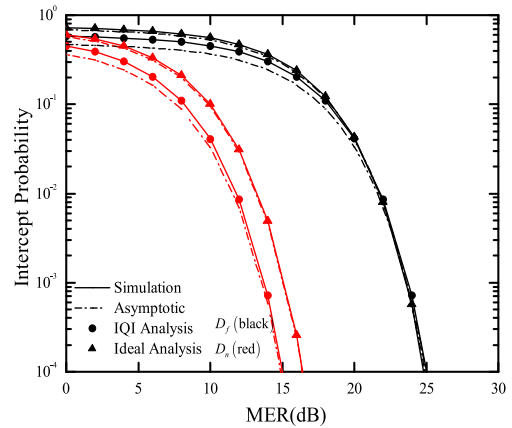


FIGURE 7. IP versus MER.

($\phi_t = \phi_r$). Note that in these results, we set $SNR = 30\text{dB}$. We can see that for a certain phase, when the amplitude increases, the change of the OP for far user and near user is less pronounced. For a certain amplitude, the OP of far user and near user increases significantly with the increase of phase. This phenomenon indicates that the reliability of the system is more sensitive to phase mismatch than it is to the amplitude mismatch. That is, the outage performance of D_f and D_n is broken as ζ_t and ϕ_t increases.

Fig. 6 shows IP versus phase mismatch ($\phi_t = \phi_r$) and amplitude mismatch ($\zeta_t = \zeta_r$). Note that in these results, we set $SNR = 15\text{dB}$. This figure indicates that the effect of amplitude mismatch and phase mismatch on IP is opposite to the OP, which means that amplitude mismatch and phase mismatch parameters can improve the secure performance of the system. In general, Fig. 5 and Fig. 6 provide a rough estimate of the maximum IQI level, and the cooperative communication system can withstand to achieve the desired reliability and security. Therefore, it can help when designing communication systems to combat undesired IQI effects.

Fig. 7 presents the IP of a cooperative NOMA system versus MER with $SNR = 20\text{dB}$. For this case, we analyze the IP and asymptotic expressions of far user and near user

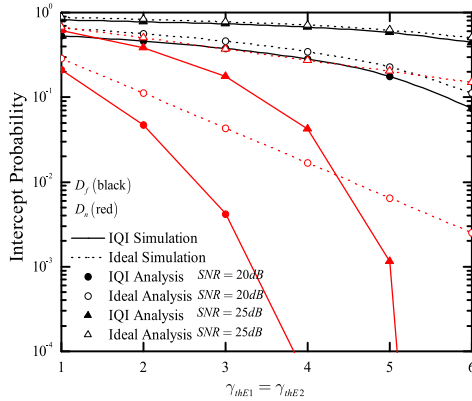


FIGURE 8. IP versus the target rate $\gamma_{thE_1} = \gamma_{thE_2}$ for different transmit SNR.

at E . It is obvious that the asymptotic expressions are strict approximation of the exact IP and the IQI effects reduced the IP of the NOMA users. We can also observe that the impact of IQI on each NOMA user is different. In this figure, we consider E performs perfect SIC, however, if E does not know the order of the users in advance, SIC will not be possible. In this case, E cannot intercept the D_n 's signal because the D_f allocates more power than the D_n .

Fig. 8 illustrates the IP versus the target rate for different transmit SNR values. For this figure, we set $MER = 5\text{dB}$ and assume that the D_f and D_n have the same target rate. One can observe that the IP of $SNR = 25\text{dB}$ is better than that of $SNR = 20\text{dB}$. In addition, we can also observe that the presence of IQI has a small impact on D_f , but has a great impact on D_n .

V. CONCLUSION

In this paper, we investigate the effects of IQI on the reliability and security for cooperative NOMA enabled IoT networks over Rayleigh fading channels. The practical factor of IQI at TX and RX are considered insightfully. Specifically, we derive the closed-form analytical expressions of the OP and IP for the far user and near user under IQI, and analyze the asymptotic OP in the high SNR region and the asymptotic IP in the high MER regime. The results obtained have been verified by Monte Carlo simulation. These results show that as the amplitude and phase parameters of the IQI increase, the user's OP increases, and the IP decreases. The user's OP decreases first and then increases as the power allocation parameter a_1 increases, that is, the performance of considered system is optimal when $a_1 \approx 0.57$. In addition, the severity of the performance degradation depends on several factors, including the power allocation ratio, the transmission SNR ratio, and the order of considered users.

APPENDIX A: PROOF OF THEOREM 1

1) Outage Probability for D_f

$$P_{out}^{D_f} = 1 - \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{thn}}, \frac{\gamma_{x_1}^{RD_f}}{\gamma_{thf}}\right) > 1\right)$$

$$= 1 - \underbrace{\Pr\left(\gamma_{x_1}^{SR} > \gamma_{thf}, \gamma_{x_2}^{SR} > \gamma_{thn}\right)}_{I_1} \underbrace{\Pr\left(\gamma_{x_1}^{RD_f} > \gamma_{thf}\right)}_{I_2}. \quad (\text{A.1})$$

Substituting (7) and (8) into (A1), then the I_1 can be written as:

$$\begin{aligned} I_1 &= \Pr\left(\gamma_{x_1}^{SR} > \gamma_{thf}, \gamma_{x_2}^{SR} > \gamma_{thn}\right) \\ &= \Pr\left(\rho_1 > M_1, \rho_1 > M_2\right) \\ &= 1 - F_{\rho_1}(M_3) \\ &= e^{-\frac{M_3}{\beta_1}}. \end{aligned} \quad (\text{A.2})$$

Substituting (13) into (A1), the I_2 of following expression can be written as

$$\begin{aligned} I_2 &= \Pr\left(\gamma_{x_1}^{RD_f} > \gamma_{thf}\right) \\ &= \Pr\left(\frac{b_1 \rho_2 \gamma_2 A_2}{b_2 \rho_2 \gamma_2 A_2 + \rho_2 \gamma_2 B_2 + C_2} > \gamma_{thf}\right) \\ &= 1 - F_{\rho_2}(M_4) \\ &= e^{-\frac{M_4}{\beta_2}}. \end{aligned} \quad (\text{A.3})$$

Substituting the expressions of I_1 and I_2 into (A1), the (21) can be obtained.

2) Outage Probability for D_n

$$\begin{aligned} P_{out}^{D_n} &= \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{thn}}\right) < 1\right) \\ &\quad + \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{thn}}\right) > 1, \min\left(\frac{\gamma_{x_1}^{RD_n}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{RD_n}}{\gamma_{thn}}\right) < 1\right) \\ &= 1 - \underbrace{\Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{thn}}\right) > 1\right)}_{I_3} \\ &\quad + \underbrace{\Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{thn}}\right) > 1\right) \Pr\left(\min\left(\frac{\gamma_{x_1}^{RD_n}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{RD_n}}{\gamma_{thn}}\right) < 1\right)}_{I_4}, \end{aligned} \quad (\text{A.4})$$

where

$$\begin{aligned} I_3 &= \Pr\left(\min\left(\frac{\gamma_{x_1}^{SR}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{SR}}{\gamma_{thn}}\right) > 1\right) \\ &= \Pr\left(\gamma_{x_1}^{SR} > \gamma_{thf}, \gamma_{x_2}^{SR} > \gamma_{thn}\right) \\ &= I_1. \end{aligned} \quad (\text{A.5})$$

Substituting (14) and (15) into (A4), then the I_4 can be written as

$$I_4 = \Pr\left(\min\left(\frac{\gamma_{x_1}^{RD_n}}{\gamma_{thf}}, \frac{\gamma_{x_2}^{RD_n}}{\gamma_{thn}}\right) < 1\right)$$

$$\begin{aligned}
&= 1 - \Pr\left(\gamma_{x_1}^{RD_n} > \gamma_{thf}, \gamma_{x_2}^{RD_n} > \gamma_{thn}\right) \\
&= e^{-\frac{M_7}{\beta_3}}.
\end{aligned} \tag{A.6}$$

Substituting the expressions of I_3 and I_4 into (A4), the (25) can be obtained.

APPENDIX B: PROOF OF THEOREM 1

Intercept Probability for D_f

$$\begin{aligned}
P_{int}^{D_f} &= \Pr\left(\gamma_{x_1}^{SR} > \gamma_{thf}, \gamma_{x_2}^{SR} > \gamma_{thn}, \gamma_{x_1}^{RE} > \gamma_{thE_1}\right) \\
&= \Pr\left(\gamma_{x_1}^{SR} > \gamma_{thf}, \gamma_{x_2}^{SR} > \gamma_{thn}\right) \underbrace{\Pr\left(\gamma_{x_1}^{RE} > \gamma_{thE_1}\right)}_{I_5} \\
&= e^{-\left(\frac{D_3}{\beta_{SR}} + \frac{E_1}{\beta_{RE}}\right)}.
\end{aligned} \tag{A.7}$$

Substituting (16) into (B1), then the I_5 can be written as $I_5 = e^{-\frac{N_1}{\beta_4}}$. Similarly, we can also obtain the IP for D_n .

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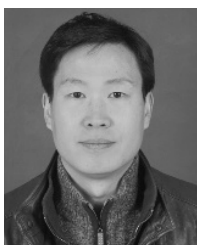
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