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1 High-resolution wetness index mapping: a useful 2 tool for regional scale wetland management

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9 ABSTRACT

Wetland ecosystems are key habitats for carbon sequestration, biodiversity and ecosystem services, yet in many they localities have been subject to modification or damage. In recent years, there has been increasing focus on effective management and, where possible, restoration of wetlands. Whilst this is highly laudable, practical implementation is limited by the high costs and unpredictable rates of success. Accordingly, there is a need for spatial information to guide restoration, ideally at the regional scale that land managers operate. In this study, we use high-resolution Light Detection and Ranging (LiDAR)-derived elevation, in conjunction with regional soil and land cover maps, to model the wetness potential of an area of conservation importance in north-west England. We use the Compound Topographic Index (CTI) as a measure for the site-specific wetness and potential to be
10 receptive to wetland restoration. The resulting model is in agreement with the regional-scale distribution of wetlands and is clearly influenced by the topographic and soil parameters. An assessment of three representative case studies highlights the small scale features that determine the potential wetness of an area. For each site, the model results conform to the expected patterns of wetness, highlighting restoration and management activity. Furthermore, areas showing high potential wetness that may be suitable for wetland habitat creation, are highlighted. The increasing availability of LiDAR data at regional and national scales will allow studies of this nature to be undertaken at previously unobtainable resolutions. Simple models, such as implemented here, benefit from explainability and relatability and have clear potential for use by managers and conservation agencies involved in wetland restoration.

Keywords: Wetlands, Spatial modelling, LiDAR, Compound Topographic Index, Restoration

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11 **1 Introduction**

12 Wetlands are among the most biodiverse and carbon-rich habitats in the northern hemisphere
13 and provide vital ecosystem services, such as flood prevention and water purification (Euliss-Jr.
14 et al. 2006; Ostle et al. 2009). They are also one the most altered ecosystems, with a long
15 history of manipulation and development (Holden, Chapman, and Labadz 2004). In Britain,
16 artificial draining of wetlands has occurred since pre-Roman times, with accelerated rates since
17 the Industrial Revolution in the early 1800s (Darby 1956; Holden, Chapman, and Labadz 2004).
18 Common drivers for this habitat loss include drainage for agricultural expansion, drying due
19 to conifer forestry, extraction for fuel or fertiliser, and water table manipulation for attempted
20 flooding control (Lindsay, Birnie, and Clough 2014; Robinson and Armstrong 1988). Peatlands
21 and lowland raised bogs, in particular, have suffered large losses, with only 338 ha of active,
22 undamaged, peat-forming bog remaining in England from a total of ~36,000 ha (JNCC 2011).

23 More recently, an increased appreciation of the ecological, hydrological and climate regulating
24 services provided by wetlands has reshaped management priorities and provided a renewed
25 focus on the maintenance and restoration of wetlands. However, restoration work is expensive
26 and success unpredictable, therefore improved data on the potential of sites to be receptive of
27 restoration efforts is pressing (Bateman et al. 2013; Mitsch and Cronk 1992).

28 On a regional scale, wetland distribution is determined by the inflow and retention of water
29 which in turn, is generally governed by topography (Beven 1997; Beven and Kirkby 1979). Beven
30 and Kirkby (1979) first proposed that site-specific moisture conditions could be modelled as a
31 function of upstream area and slope steepness; this Compound Topographic Index (CTI) has
32 proved an effective metric for a range of geomorphic, ecological, and hydrological purposes. The
33 CTI, and it's modifications, have been used to map the current and potential wetness for a range
34 of locations and environments including: continental Europe (riparian woodlands and grasslands,
35 mires; Merot et al. 2003), northern Sweden (mires; Rodhe and Seibert 1999), and the eastern
36 United States (wet woodlands; Lang et al. 2013)

37 Over the last decades, topographic modelling has been aided by the free availability of
38 global coverage Digital Elevation Models (DEMs), products such as the USGS GTOPO30 (~1
39 km resolution), NASA STRM (~30 and ~90 m resolution), and NASA/JAXA ASTER DEM
40 (30 m), all of which allow regional analyses at minimal expense and computation. However,
41 these resolutions are more suited for hydrological applications focusing on general patterns of
42 water movement (Beven 1997). For ecological studies, finer scale data sources are needed to
43 discriminate small-scale features (Rodhe and Seibert 1999; Sørensen and Seibert 2007).

44 In recent years, the advent of Light Detection And Ranging (LiDAR) technology has greatly
45 increased the availability of high-resolution (< 10 m) elevation data. This has facilitated a shift

46 in focus towards small scale, site-specific hydrology and the resulting vegetation (Moeslund
47 et al. 2013). The high cost of LiDAR data has historically limited this resource to small areas
48 (e.g. Lane et al. 2003; Maxa and Bolstad 2009). However, national-scale acquisition plans
49 combined with open data policies for a number of countries now enables large-scale monitoring
50 at previously unobtainable resolutions. In England, the Environment Agency recently made
51 0.25 - 2 m resolution DEMs derived from LiDAR freely available, offering a valuable resource for
52 hydrological modelling.

53 In this study, we use high-resolution (4 m) LiDAR-derived elevation data to map potential
54 wetland habitats across the wider Greater Manchester region, Northwest England. This is the
55 first high-resolution regional-scale effort to map wetland potential. Our main objectives are: 1) to
56 identify areas of potential wetland habitats in the Greater Manchester region, 2) test the modelled
57 outputs at smaller site-scales, and 3) explore the strengths and limitations of high-resolution
58 CTI maps. Results from this study will aid local conservation organisations in making informed
59 decisions on the continued management and potential restoration of the region's wetlands.

60 **2 Materials and Methods**

61 **2.1 Study Area**

62 Our study area is located in Northwest England, ranging from the Mersey basin in the south
63 to the West Pennine Moors in the north (Figure 1). This region has a mild oceanic temperate
64 climate (Köppen-Geiger classification: Cfb, (Kottek et al. 2006) with mean annual rainfall of
65 867 mm/year and a mean monthly maximum temperature of 13.2 °C. The climate is broadly
66 constant across the study area, with a slight west-east increase in rainfall (Met Office 2016).
67 Topographically, the area varies from the undulating West Pennine Moors in the north-east (up to
68 456 m asl), to the relatively flat plains bordering the Mersey basin in the south (around 10 m asl).

69 The area encompasses around 48,000 ha of varied wetland habitats from open water, fen,
70 reed beds, and marshes to blanket and lowland raised bogs, many of which have been subjected
71 to development or modification in the past 100 years. The area is a designated Local Nature
72 Improvement Area (NIA) and managed under the Great Manchester Wetlands Partnership. The
73 ecological goal of this partnership is to restore wetland habitats and habitat connectivity to
74 support species movements across the area and increase carbon sequestration and storage.
75 These opportunities exist across a variety of sites from ex-brownfield areas, including coal
76 measures, agricultural grasslands and cutover peatlands.

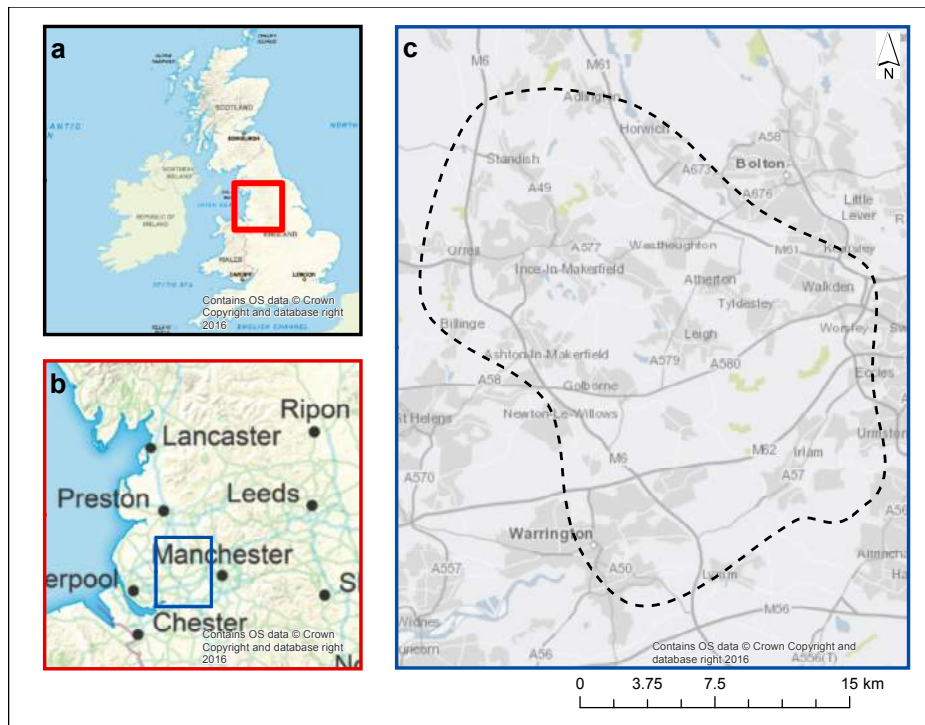


Figure 1. Study area in a) the UK, b) Northwest England, and c) The wider Great Manchester area, the dashed line delineates the Nature Improvement Area for the Great Manchester Wetlands

77 2.2 Data

78 2.2.1 Digital Elevation Model

79 In England, the Environment Agency provides high-resolution LiDAR- derived Digital Terrain
 80 Models (DTMs) covering roughly 75% of the country. These DTMs are produced from aerial
 81 LiDAR surveys, with final products composited from surveys undertaken between 1998 and
 82 2015, **with the most recent observations taking precedence**. The error range for the composited
 83 layers is ± 40 cm in the planar (xy) dimension, and ± 15 cm (root-mean-square error) or ± 5 cm
 84 (random) for the vertical (z) dimension. **Different survey flights were combined by applying a 30**
 85 **m feathering overlap to ensure a seamless integration**. In this study, we used the 2 m resolution
 86 composited DTM product, aggregated to 4 m to reduce computation time.

87 2.2.2 Soils

88 Soil data were obtained from the National Soil Resources Institutes's Soil Map (NSM) (Mayr
 89 and Palmer 2006). This database groups soils into 27 units, at a 1:50,000 scale. **Each unit**
 90 **possesses an accompanying drainage classification (low-high), determined through analysis of**
 91 **field surveys and historical data**. These classifications were aggregated into six new categories,
 92 based on their drainage characteristics (Table 1).

93 **2.2.3 Land Cover**

94 Land cover data were extracted from the National Land Cover 2007 (LCM2007) product, pro-
95 duced by the Centre for Ecology and Hydrology. This is a 25 m resolution map featuring 23
96 land cover types for the United Kingdom (Morton et al. 2011). Produced from an amalgamation
97 of Landsat, SPOT, IRS-LISS3, and AWIFS satellite imagery, combined with extensive ground
98 reference survey data, the LCM-2007 data are consistent with national cartographic boundaries
99 (Morton et al. 2011). Land cover types were aggregated into four classes (**very high, moderate,**
100 **low, very low**) based on their drainage potential (Table 1). **These classes were determined based**
101 **on the generalised ability of the land to withhold water: with 'very high' indicating complete im-**
102 **permeability, whilst 'very low' classes have continual standing water. To enable the transferability**
103 **of methods, groupings were kept broad.**

104 **2.2.4 Priority Habitat Inventory**

105 The locations of known verifiable wetland habitats were acquired from the Priority Habitat Inven-
106 tory (PHI), maintained by Natural England (Natural England 2016). This is a spatial database for
107 habitats of conservation importance within England, **locations are manually surveyed by regional**
108 **specialists based on Biodiversity Action Plan (BAP) requirements.** We selected all records
109 corresponding to wetland environments resulting in nine classes. Whilst not encompassing
110 all known wetland sites, the PHI allows us to undertake a regionally representative validation
111 exercise.

112 **2.3 The Compound Topographic Index**

113 The Compound Topographic Index (CTI), **also known to as the Topographic Wetness Index**
114 **(Hengl, Gruber, and Shrestha 2003)**, is a simple hydrological metric for quantifying the steady-
115 state wetness of an area. For a given **raster cell i** , it is defined as:

$$CTI_i = \ln \frac{\alpha_i}{\tan \beta_i} \quad (1)$$

116 where α is the up-stream contributing area (**m^2 per unit flow width perpendicular to the flow di-**
117 **rection**) and β is the corresponding slope (radians) (Beven and Kirkby 1979). **These components**
118 **are derived from the DEM, by the process shown in Figure 3.** Hydrologically, this formula relates
119 the potential of an area to receive water (α) against potential loss or retention of moisture (β). By
120 dividing the up-stream contributing area, i.e. the up-slope drainage area, by the corresponding
121 slope, CTI values are proportional to the potential wetness and lateral transitivity of a site. The
122 larger the CTI, the greater potential for the landscape to hold water. Although a simplistic metric,

Drainage Potential	Land Cover	Soil
Very High (6)	Inland rock, urban, suburban	Freely draining slightly acid sandy (loamy); Sand dunes
High (5)		Slightly acid loamy and clayey soils with impeded drainage
Moderate (4)	Arable and horticulture, improved/rough/natural/acid grassland	Naturally wet very acid sandy and loamy
Low-Moderate (3)		Slowly permeable seasonally wet acid loamy (base-rich loamy) and clayey
Low (2)	Broadleaved/coniferous woodland, heather/heather grassland	Blanket/raised bog peat soil
Very Low (1)	Fen, marsh, swamp, bog	Very acid loamy upland soils with a wet peaty surface

Table 1. Drainage classification of soil and land cover data. Soil rankings are taken from the National Soil Map database (Mayr and Palmer 2006), land cover types are grouped based on hydrological similarities. **Only soil and land covers present in the study area are mentioned**

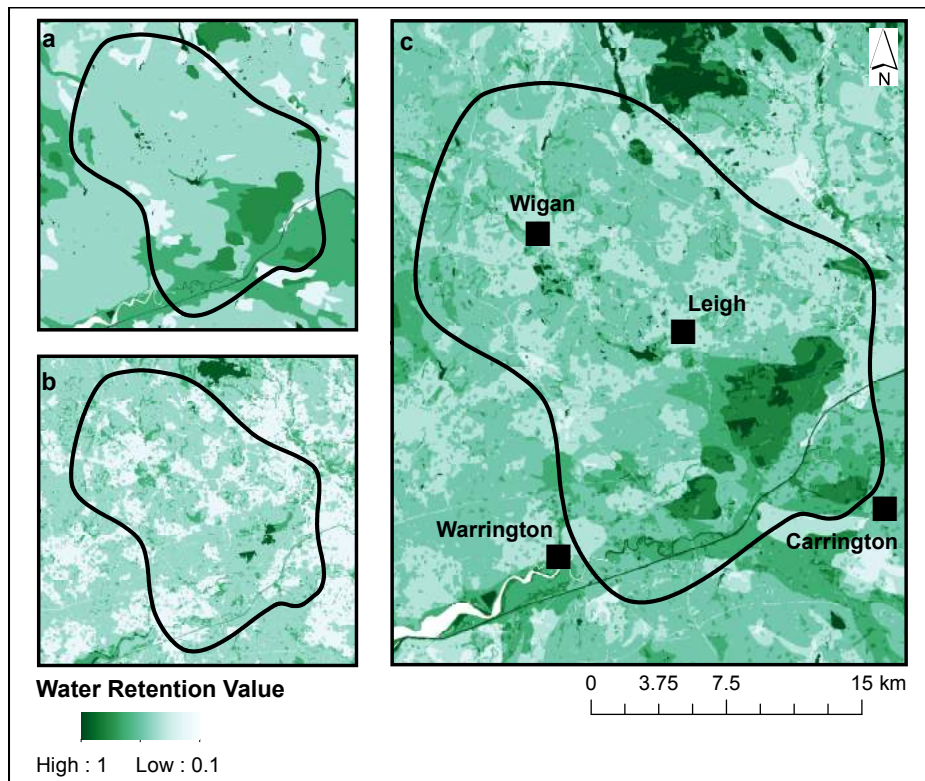


Figure 2. Drainage scores for a) soil, b) land cover, and c) combined soil and land cover

123 CTI values have been shown to be indicative of soil organic matter, erosion potential, and wetland
 124 extent (Beven 1997; McKenzie and Ryan 1999).

125 We calculated the CTI for the Great Manchester NIA region, using the LiDAR DEM, as detailed
 126 in Figure 3. The slope layer is calculated based on the maximum difference between each pixel
 127 and the eight neighbours. Flow direction was determined by using a eight direction (D8) model,
 128 whereby flow is assumed to follow the steepest decent based on the neighbouring eight cells
 129 (Garbrecht and Martz 1997). The number of cells that flow into a pixel is summed to calculate
 130 the flow accumulation. This is then converted into the up-slope contributing area by adding 1,
 131 to account for the candidate pixel, and multiplying by the DEM cellsize. The up-slope contributing
 132 area can weighted to account for varying levels of drainage received from neighbouring pixels.
 133 We created an aggregated water retention layer from the land cover and soil datasets (Figure 2),
 134 based on a scaled sum of the drainage potential values in Table 1. A high weighting value will
 135 simulate the retention of water; for example, due to peaty soil or forest cover. Conversely, low
 136 weighting values associated with sandy soils and impervious land cover will encourage the loss
 137 of water. Thus accommodating varying overland flow and hydraulic conductivity rates present in
 138 a region, providing a more realistic representation. To reduce uncertainty in the weight layer, the
 139 individual drainage classes were kept generalised, so that only the main regional patterns were

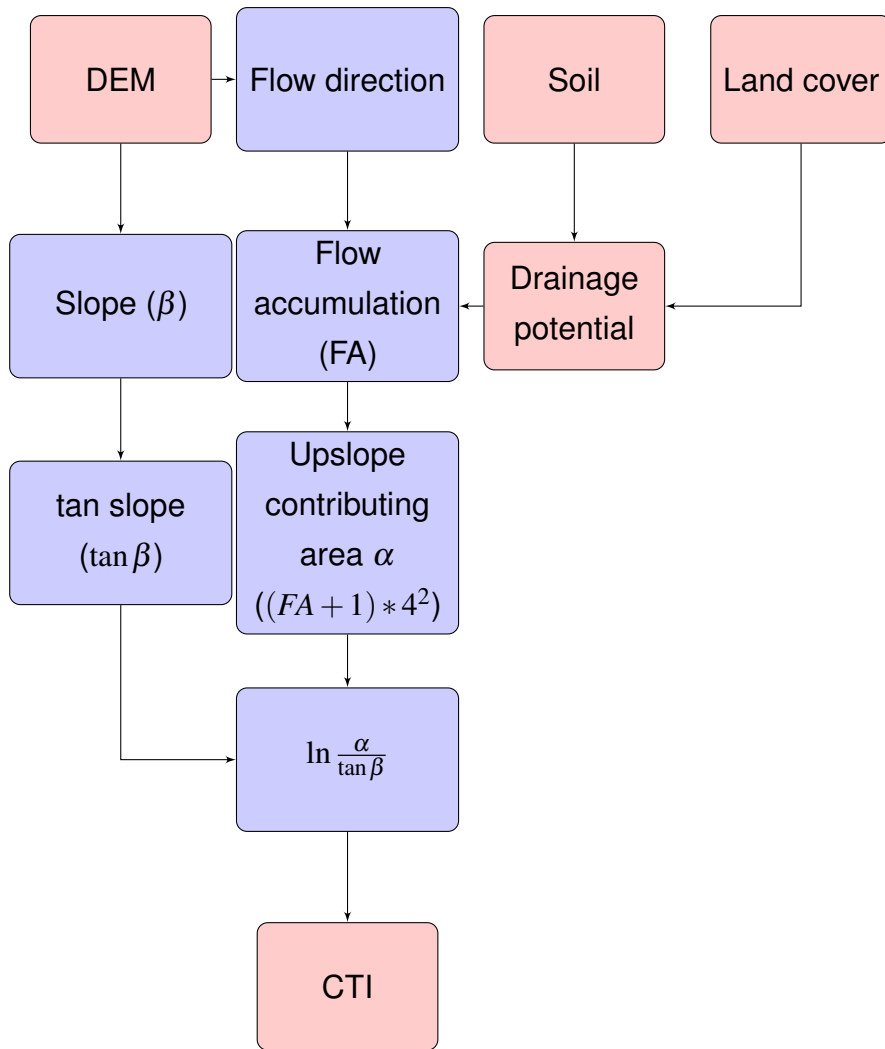


Figure 3. Flowchart of the process for generating the Compound Topographic Index from the DEM

140 captured.

141 Processing was undertaken using the free and open source software packages of "TauDEM"
 142 (Tarboton 2005) and "raster" (Hijmans 2016) within the R Statistical Computing Environment (R
 143 Core Team 2016).

144 To validate the derived CTI layer, 3000 random points were selected for: i) generic non-
 145 wetland areas, and ii) each wetland class from the PHI. Analysis of Variance (ANOVA) was
 146 used to test for a significant difference between these groups, with a post-hoc Tukey's Honest
 147 Significant Difference (HSD) test used to identify group-level differences.

3 Results and Discussion

3.1 Regional Overview

The Great Manchester wetlands region displays a wide range of wetness potential values, as derived from the CTI output (Figure 4). The CTI scores have a range of 0 to 28, $\bar{x} = 8.30$ and $SD = 2.51$. The overall distribution of CTI values reflects the topological variation of the region, with the highest scores (dark blue areas in Figure 4) falling into several categories. High scoring pixels north-west of Carrington (Figures 5a and 5b) are dominated by lowland peats, high values between Wigan and Leigh correspond to subsistence induced lakes and reed beds (Figure 5c), whilst the area west of Bolton is characterised by upland raised peats in the West Pennine Moors. Low scoring areas (light yellow in Figure 4) correspond to urban and built-up areas, with road and rail networks appearing as very low values. These patterns relate to the broad-scale distribution of wetlands in the regions, and highlight the role of auxiliary data in the form of soil and land cover maps to guide the topographic index modelling.

The clear distinction of landscape-scale patterns is reassuring. A number of studies have observed that when using high-resolution DEMs regional patterns are obscured by local micro-topographic variation (Drover et al. 2015; Sørensen and Seibert 2007; Wolock and Price 1994). This is normally attributed to a reduction in the up-slope drainage area as calculated when using smaller pixels (Sørensen and Seibert 2007). The success of our model in this regard could be attributed to a number of factors: our considerably larger study area compared, to previous studies, should increase the up-slope drainage area, reducing the influence of small-scale features. Furthermore, the high accuracy and precision of the LiDAR data should allow flow patterns to navigate potential blockages that would be obscured by coarse DEMs.

The CTI outputs for wetland and non-wetland sites (Figure 6) indicates that the designated areas generally have higher values. This is supported by the ANOVA results which highlighted a significant difference between the groups ($F = 268.5$, $P < 0.05$). However, not all classes were significantly different from the non-wetland samples (Tukey's HSD > 0.05 , black squares in Figure 6 indicate significant differences). This can partially be explained by the nature of sites included in the PHI: many blanket bogs are designated to facilitate restoration efforts, and therefore, have low water retention and CTI values. Comparably, mudflats are commonly situated on tidal rivers and estuaries (e.g the Mersey) and have limited topographic-induced wetness.

To provide a site-specific insight on the potential and limitation of CTI outputs for characterising wetlands at a regional scale, we analysed three case study sites that are representative of local wetland habitats and are the focus of on-going conservation and restoration efforts: Carrington Moss, Risley Moss, and the Wigan Flashes (Figure 5).

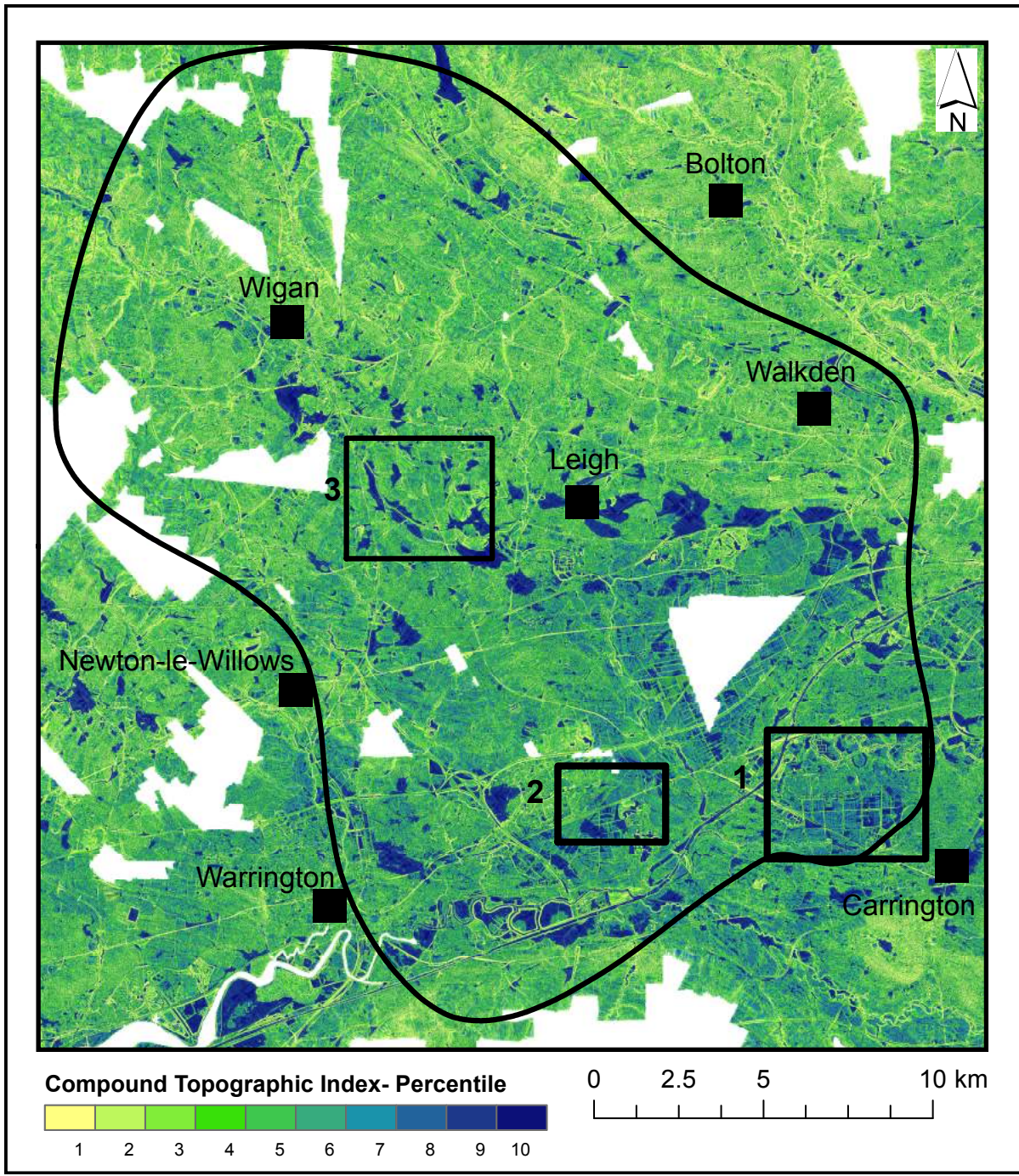


Figure 4. Regional Compound Topographic Index values. Black line is the boundary of the Great Manchester Wetlands Partnership. Boxes 1-3 refer to the subsets in Figure 5. White areas indicate the lack of LiDAR coverage.

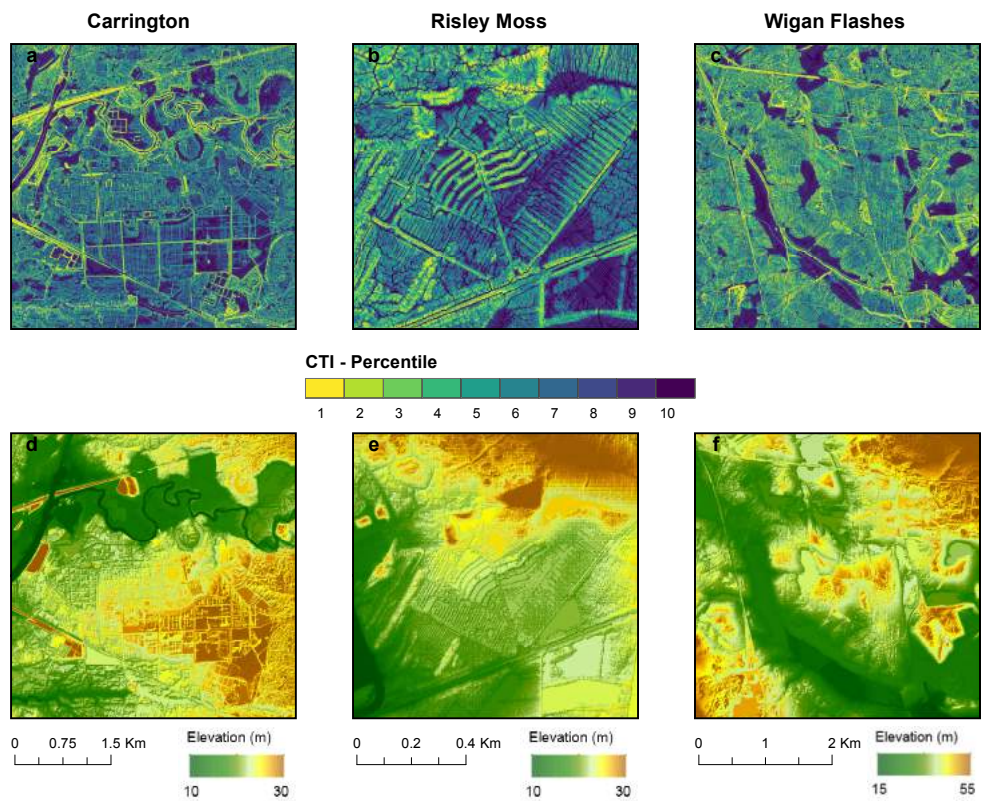


Figure 5. (a-c) Compound Topographic Index subset maps; (d-f) Respective DEM subsets.

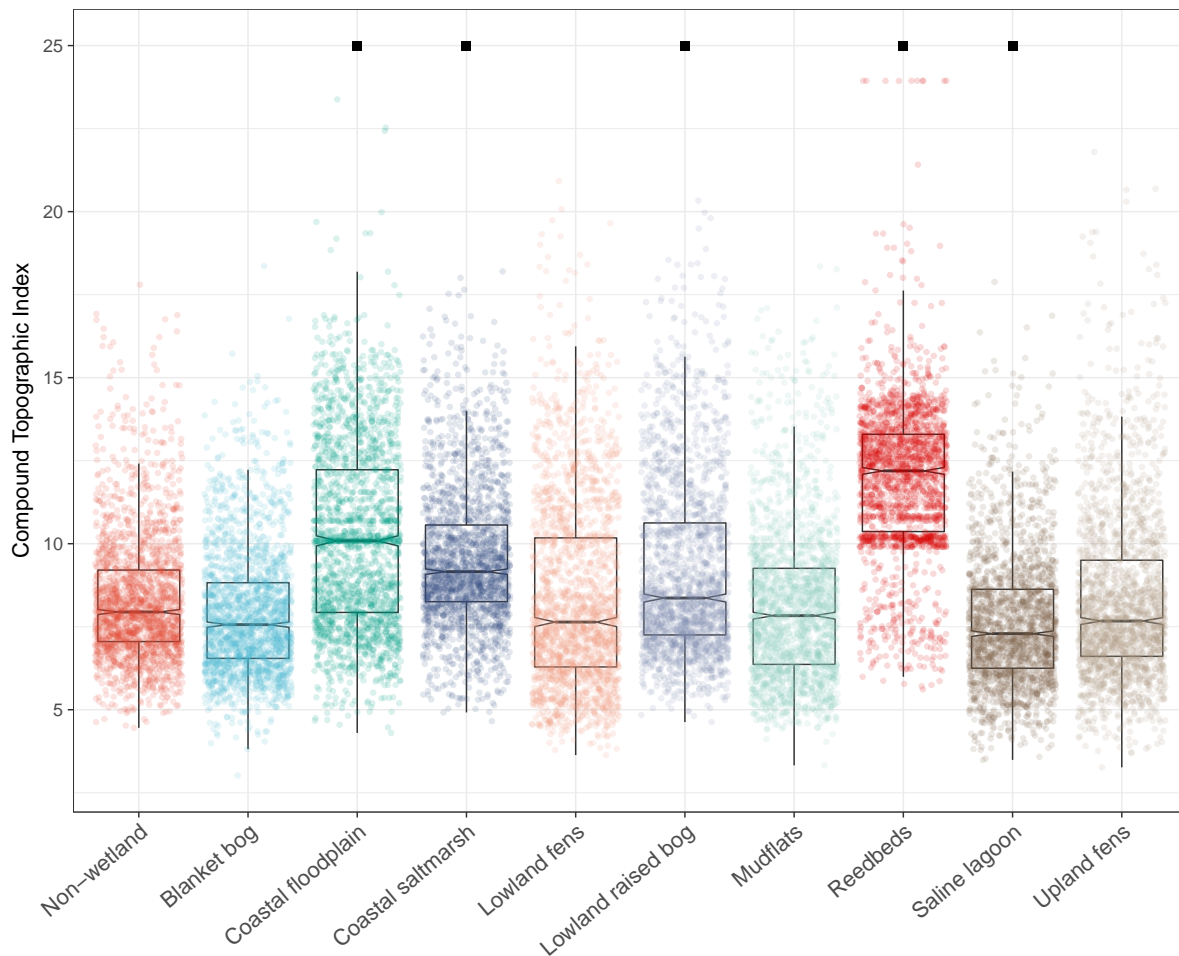


Figure 6. CTI values for 3000 random points per wetland category compared to non wetland. Black squares indicate a significant difference between the relevant class and non-wetland according to post-hoc Tukey's HSD test ($P < 0.05$)

182 **3.2 Case Studies**

183 **3.2.1 Carrington Moss**

184 Carrington Moss is a lowland raised peat bog in the south-west of the wider study area. The
 185 generally flat topography of this site has enabled a range of developments over the past 200
 186 years, including night-soil disposal, agriculture, chemicals processing and sporting facilities.
 187 This area is now a priority location for new housing developments. A combination of water
 188 retentive peat soils and generally flat topography results in high potential wetness across much
 189 of this area. This is to be expected as active drainage is required to enable arable farming: the
 190 drainage ditch grid is visible in **the bottom right of** Figure 5a. The dominant peat soil unit does
 191 not display homogeneous CTI values, with southern and eastern segments featuring higher

192 scores, highlighting the role of agricultural drainage. Furthermore, the sections immediately
193 south of the River Mersey (**basin visible in the top of Figure 5.d**) have been heavily damaged
194 by industrial facilities, demonstrating markedly lower wetness scores than the agricultural land.
195 Wetland restoration in this area would therefore be most effective on the agricultural land, where
196 the removal of drainage would facilitate water retention. Regardless of the underlying peat soils,
197 the formerly industrialised sites have low water acculturation potential.

198 **This case study highlights the potential of CTI-style models to identify small-scale drainage**
199 **infrastructure that may inhibit restorations and re-wetting efforts. Identifying these features by**
200 **manual surveying would be highly arduous and time-consuming. Simple topographic model**
201 **allow the entire site to be assessed rapidly, so many planned works can be strategically directed.**

202 **3.2.2 Risley Moss**

203 Risley Moss is a remnant segment of a lowland raised bog system that previously extended
204 through southern Lancashire and northern Cheshire. The site consists of woodland inter-
205 spersed with meadows and degraded peat-based mossland for which it is nationally designated
206 (*Risley Moss SSSI Designation*). **The main dome segment is located in the centre of Figure**
207 **5b and 5e.** The historically high water table at the site prevented agricultural development, and
208 usage mainly focused on forestry and peat cutting. By the end of peat extractions works, the
209 site was severely degraded, with the base heavily terraced and an elevated central section
210 of drying peat unable to retain water. Since the 1970s, there has been a continued effort to
211 increase the water table for this portion of the bog and prevent further drying of the site (Ross and
212 Cowan 2003). This work has focussed on topographic modification by re-contouring the surface
213 using bunds and scrapes along the dome surface. These can be seen in the "herring bone"
214 pattern **located at the centre of** Figures 5b and 5e. These features aim to restore the peat by
215 promoting water retention through accumulation in the hummocky terrain. The relative success
216 of restoration work is visible in the CTI map. Large features established in the 1990s show a
217 clear trench system (branching out from the dome centre, 5b and 5e), with pronounced variation
218 between very wet trenches and drier ridges. These conditions are undesirable for restoration
219 due to low potential for keystone species, such as Sphagnum mosses, to colonise either the dry
220 crests or the deep pools (McNeil and Waddington 2003). Conversely, works undertaken more
221 recently have a much shallower network of excavations (middle-right of Figure 5b), resulting in
222 a more homogeneous wetness score. These areas are more favourable for Sphagnum moss
223 species and exhibit reduced (or reducing) cover of dry tolerant plants, e.g. purple moor grass
224 *Molinia caerulea*.

225 **This case study displays the ecohydrological potential of simple topographic models, by**
226 **highlighting the relative success or limitations of the restoration work. The scale of data employed**

227 here is particularly relevant as the small-scale variations between the restoration works would
228 be obscured under a coarse DEM (Rodhe and Seibert 1999). As microscale topography is
229 an important factor for greenhouse gas flux and soil properties in peat bogs, LiDAR data has
230 good potential for modelling these processes at higher resolutions (Rothwell and Lindsay 2007;
231 Sundqvist et al. 2015).

232 **3.2.3 Wigan Flashes**

233 The Wigan Flashes in Figures 5c and 5f are patches of mining-induced subsidence that have
234 developed into a series of open water ponds, wet grasslands, reed beds, and marshes. Initially,
235 this subsidence resulted in the area accumulating pollution and being used as spoil heaps
236 (Gemmell and Connell 1984). Over the last 20 years, clean-up efforts combined with de-
237 industrialisation have transformed the habitat, leading to national designations for wildfowl
238 assemblages and wetland habitats (Natural England 1990). ~~As newly formed wetlands, less~~
239 ~~than 50 years old, there has been minimal intentional degradation or development.~~ Many of
240 the existing flashes display high CTI values indicating their high wetness potential due to the
241 depressed terrain. Interestingly, many other plots feature comparable values including locations
242 that would not typically be considered ideal wetland habitat, such as an industrial estate showing
243 high values in the south-east (**bottom-right**) of Figure 5c.

244 In recent years, this site has become regionally important for bird and water vole communities
245 (Champion and Ashton 2010; Powell and Milburn 2011). Due to their location, spanning both
246 the urban landscape intersecting the Mersey and Ribble watershed and bridging the upland-
247 lowland transitions, the Wigan Flashes may play a major role in ensuring connectivity for wetland
248 species across these zones. Designing conservation corridors to enable species connectivity
249 is a challenging endeavour, especially in urbanised environments; the provision of information
250 on areas potentially receptive to developments is, therefore, desirable. However, in order to be
251 successful, restoration ecology must be considered within the local social context. For the Wigan
252 Flashes, a considerable amount of the works undertaken have been initiated by local wildlife
253 groups and volunteers, such as the Wildlife Trusts. ~~Therefore, in order to be useful, scientific~~
254 ~~advice must be simple, understandable, and reliable.~~ During the completion of this work, the
255 potential and limitations of using CTI maps was discussed with local operatives who found the
256 simplicity and relatable nature of the outputs to be beneficial and appropriate for their work.
257 **This highlight the communication benefits of high-resolution yet simple models. These can be**
258 **easily understood by the general public, providing evidence to encourage stakeholder buy in on**
259 **restoration projects.**

3.3 Potential Applications and Future Work

The restoration and maintenance of wetland habitat is a challenging and expensive undertaking. The provision of regional-scale spatially explicit data to inform conservation efforts is, therefore, beneficial (Mitsch and Wilson 1996). We envisage a number of ways in which the methods and outputs of this study may be of use. Firstly, high-resolution spatial information can inform decisions regarding the commencement of restoration work. Whereas many former wetland sites are known by local authorities, elucidating the potential receptiveness of these sites to remediation can be an expensive and time consuming task when undertaken by field surveying. Models such as the CTI may offer a quick and low-cost alternative. This would be particularly appropriate where small-scale features (such as peat grips) affect hydrology, resulting in variable water retention over small areas; the Carrington and Risley Moss case studies would typify this. Given the expense of purchasing land and the often hit-and-miss nature of wetland reclamation works, it is essential that efforts be focused on plots which are most likely to succeed (Mitsch and Wilson 1996). The precise method of selecting plots would be determined by the objectives of the restoration work (e.g. species connectivity, carbon storage, flood prevention), yet in any case, easily accessible information on potential wetness would be a valuable resource to inform decisions (Bateman et al. 2013).

Secondly, the availability of high-resolution DEMs enables simulations of proposed developments to be undertaken. By modifying the original DEM to represent proposed developments, such as the blocking of drainage ditches, changes in surface flow and in the wetness potential can be rapidly assessed, thus ensuring the most appropriate allocations of efforts and funds.

Finally, wetlands support a large number of species, many of which require varying degrees of connectivity between habitat patches (Zinko et al. 2005). Focusing on known networks may overlook potentially important areas in unexpected or counter-intuitive locations. By employing broad-scale analyses, all potentially wet habitats can be evaluated and species distribution models adjusted accordingly.

Many studies have employed topographic information, often in conjunction with auxiliary or satellite data, to classify wetland habitats (Babbar-Sebens et al. 2013; Bwangoy et al. 2010). However, quantifying potential habitats is more complex, due to the uncertainty of projections. The approach developed here has a number of benefits over previous methods. Firstly, our approach is based on physical processes (water retention and accumulation) with a long hydrological usage, making the model transparent. Models developed in the future will therefore be comparable and unaffected by changes in e.g. land cover classification schemes. Secondly, by using a high-resolution DEM our models can be sense-checked easily, allowing areas with spurious results to be discarded; this would not be possible using an amalgamation of coarse-

295 resolution auxiliary datasets e.g. (Schleupner and Schneider 2013; Van Lonkhuyzen, LaGory,
296 and Kuiper 2004).

297 **4 Conclusions**

298 Wetlands are critical for biodiversity, hydrology and carbon storage. There is, therefore, growing
299 interest in the restoration and creation of new wetland habitats. The provision of spatially explicit
300 data to inform management is important to ensure the most ecologically and financially sound
301 decisions are made and actions undertaken. In this study, we used high-resolution elevation
302 data, in combination with regional land cover and soil maps, to model potential wetness of
303 the wider Great Manchester Local Nature Improvement Area. The results showed generally
304 higher values for existing wetlands, and also highlighted areas with high potential wetness, where
305 restoration works may be successful, at both regional and local site scales. An increasing number
306 of national mapping agencies are making LiDAR data freely available for scientific research,
307 enabling improved prioritisation of wetland restoration and management.

308 **5 Acknowledgements**

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